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Formulation and analysis of fully-mixed methods for stress-assisted diffusion problems*

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Abstract

This paper is devoted to the mathematical and numerical analysis of a mixed-mixed PDE system describing the stress-assisted diffusion of a solute into an elastic material. The equations of elastostatics are written in mixed form using stress, rotation and displacements, whereas the diffusion equation is also set in a mixed three-field form, solving for the solute concentration, for its gradient, and for the diffusive flux. This setting simplifies the treatment of the nonlinearity in the stress-assisted diffusion term. The analysis of existence and uniqueness of weak solutions to the coupled problem follows as combination of Schauder and Banach fixed-point theorems together with the Babuška-Brezzi and Lax-Milgram theories. Concerning numerical discretization, we propose two families of finite element methods, based on either PEERS or Arnold-Falk-Winther elements for elasticity, and a Raviart-Thomas and piecewise polynomial triplet approximating the mixed diffusion equation. We prove the well-posedness of the discrete problems, and derive optimal error bounds using a Strang inequality. We further confirm the accuracy and performance of our methods through computational tests.

Keywords: A priori error analysis; augmented fully-mixed formulation; stress-diffusion coupling; finite element methods; fixed-point theory.

Mathematics subject classifications (2000): 65N30, 65N12, 65N15, 76R05, 76D07.

1 Introduction

We are interested in the mathematical and numerical study of a stationary problem representing diffusion-deformation processes where the stress acts as a coupling variable. So-called stress-assisted diffusion models (derived from thermodynamic principles and phenomenological arguments in e.g. [1, 30]) are relevant to numerous applications including diffusion of boron and arsenic in silicon [27], hydrogen diffusion in metals [36], voiding of aluminum conductor lines in integrated circuits [38], strain-aging measurements in iron [28], sorption in polymers [32], to name a few. Of special appeal to us is the study of microscopic electrode damage in lithium ion batteries [5, 11, 22, 26, 34]. When

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lithium diffuses into a secondary particle (an anode made of e.g. silicon), its core expands and its elastic response, also with that of neighboring particles and the surrounding electrolyte, modify the diffusive properties inside the medium. If the process is confined inside the anode, then the electric field is practically constant and the system may be described solely in terms of diffusion and stress.

Regarding the mathematical and numerical analysis of related models, the literature is rather scarce. Some recent references include homogenization of concentration - electric potential systems [35], multi-scale analysis of the deterioration of binder in electrodes [15], and a general local-global well-posedness theory [25]. Differently from these approaches, in [18] we have recently proposed a mixed-primal formulation for stress-assisted diffusion. The model covers the linear elastic regime, it incorporates the rotation tensor as supplementary variable serving to impose stress symmetry in a weak manner; and this mixed problem is coupled with a primal formulation for diffusion. Here, in contrast, we consider an augmented mixed formulation for the diffusion equation and we consider a slightly different set of boundary conditions, motivated by the specific application into lithium batteries. Similarly to [20], the concentration gradient and the diffusive flux are incorporated as auxiliary unknowns, which allows us to treat the stress-dependent diffusivity using a dual-mixed setting. In order to apply the regularity estimates from [18], we augment the formulation with redundant terms arising from a constitutive equation. Next, following the approach introduced in [3], we combine fixed-point arguments, regularity estimates, the Babuška-Brezzi theory, the Lax Milgram lemma, the Sobolev embedding and Rellich-Kondrachov theorems, and small data assumptions to establish existence and uniqueness of solution of the continuous problem. The solvability of the Galerkin scheme follows from the Brouwer fixed-point theorem and properties of the finite element subspaces. Finally, the convergence analysis is conducted adapting Strang inequalities, Céa estimates, and using approximation properties of the finite element spaces.

The rest of the paper is organized as follows. In Section 2 we describe required notation and functional spaces to be employed along the paper. Then, we introduce the model problem and requirements on the specific constitutive functions. Next, in Section 3 we derive the augmented fully-mixed formulation and establish its well-posedness. The Galerkin scheme and the existence of discrete solution are then studied in Section 4. In addition, under similar assumptions we deduce error bounds; and we close in Section 5 with a numerical example that confirms the theoretical rates of convergence, and a second tests studying the applicability of the discrete formulation in the simulation of 3D microscopic lithiation processes.

2 The model problem

Let $\Omega \subseteq \mathbb{R}^n$, $n \in \{2, 3\}$, be a given bounded domain with polyhedral boundary $\partial\Omega = \bar{\Gamma} \cup \bar{\Sigma}$, with $\bar{\Gamma} \cap \bar{\Sigma} = \emptyset$ and $|\bar{\Gamma}|, |\bar{\Sigma}| > 0$, and denote by $\boldsymbol{\nu}$ the outward unit normal vector on Γ . Standard notation will be adopted for Lebesgue spaces $L^p(\Omega)$ and Sobolev spaces $H^s(\Omega)$ with norm $\|\cdot\|_{s,\Omega}$ and seminorm $|\cdot|_{s,\Omega}$. In particular, $H^{1/2}(\partial\Omega)$ is the space of traces of functions of $H^1(\Omega)$ and $H^{-1/2}(\partial\Omega)$ denotes its dual. By \mathbf{M}, \mathbb{M} we will denote the corresponding vectorial and tensorial counterparts of the generic scalar functions space M and as usual, $|\cdot|$ denotes both the Euclidean norm in \mathbb{R}^n and the Frobenius norm in $\mathbb{R}^{n \times n}$. Let $\mathbf{div} \boldsymbol{\tau}$ be the divergence operator acting along the rows of the tensor $\boldsymbol{\tau}$. We recall that the tensorial $H(\mathbf{div})$ space

$$\mathbb{H}(\mathbf{div}; \Omega) := \{ \boldsymbol{\tau} \in \mathbf{L}^2(\Omega) : \mathbf{div} \boldsymbol{\tau} \in \mathbf{L}^2(\Omega) \},$$

equipped with the norm $\|\boldsymbol{\tau}\|_{\mathbf{div};\Omega}^2 := \|\boldsymbol{\tau}\|_{0,\Omega}^2 + \|\mathbf{div}(\boldsymbol{\tau})\|_{0,\Omega}^2 \quad \forall \boldsymbol{\tau} \in \mathbb{H}(\mathbf{div}; \Omega)$, is a Hilbert space.

Let \mathbb{I} stand for the identity tensor in $\mathbb{R}^{n \times n}$. For any tensors $\boldsymbol{\tau} = (\tau_{ij})_{i,j=1,n}$, and $\boldsymbol{\zeta} = (\zeta_{ij})_{i,j=1,n}$,

we denote the transpose, trace, tensor product, and deviatoric tensor, respectively, as

$$\boldsymbol{\tau}^t := (\tau_{ij})_{i,j=1,n}, \quad \text{tr}(\boldsymbol{\tau}) := \sum_{i=1}^n \tau_{ii} \quad \boldsymbol{\tau} : \boldsymbol{\zeta} := \sum_{i,j=1}^n \tau_{ij} \zeta_{ij}, \quad \text{and} \quad \boldsymbol{\tau}^d := \boldsymbol{\tau} - \frac{1}{n} \text{tr}(\boldsymbol{\tau}) \mathbb{I}.$$

Finally, we will denote by $\|\cdot\|_{\infty, \Omega}$ the norm of the Banach space $L^\infty(\Omega)$ as well as of its vectorial version $\mathbf{L}^\infty(\Omega)$.

Let us consider the following system of PDEs, governing the diffusion of a solute interacting with the motion of an elastic solid occupying the domain Ω :

$$\boldsymbol{\sigma} = \lambda \text{tr} \boldsymbol{\varepsilon}(\mathbf{u}) \mathbb{I} + 2\mu \boldsymbol{\varepsilon}(\mathbf{u}) \quad \text{in } \Omega, \quad -\text{div } \boldsymbol{\sigma} = \mathbf{f}(\phi) \quad \text{in } \Omega, \quad (2.1)$$

$$\tilde{\boldsymbol{\sigma}} = \vartheta(\boldsymbol{\sigma}) \nabla \phi \quad \text{in } \Omega, \quad -\text{div } \tilde{\boldsymbol{\sigma}} = g(\mathbf{u}) \quad \text{in } \Omega, \quad (2.2)$$

$$\mathbf{u} = \mathbf{u}_D \quad \text{on } \Gamma, \quad \boldsymbol{\sigma} \boldsymbol{\nu} = \mathbf{0} \quad \text{on } \Sigma, \quad (2.3)$$

$$\phi = \phi_D \quad \text{on } \Sigma, \quad \tilde{\boldsymbol{\sigma}} \cdot \boldsymbol{\nu} = 0 \quad \text{on } \Gamma. \quad (2.4)$$

Equations (2.1) state the constitutive relation and momentum balance for the elasticity equations, problem (2.2) defines the diffusion equation and diffusive flux, and (2.3)-(2.4) provide a specification of the boundary treatment on each part of the boundary, where $\mathbf{u}_D \in \mathbf{H}^{1/2}(\Gamma)$ and $\phi_D \in H^{1/2}(\Sigma)$. The involved quantities and model parameters are the Cauchy solid stress $\boldsymbol{\sigma}$, the displacement field \mathbf{u} , the infinitesimal strain tensor $\boldsymbol{\varepsilon}(\mathbf{u}) := \frac{1}{2} (\nabla \mathbf{u} + \nabla \mathbf{u}^t)$, the Lamé constants $\lambda, \mu > 0$ characterizing the material, the diffusive flux $\tilde{\boldsymbol{\sigma}}$, the solute concentration ϕ , the tensorial diffusivity $\vartheta : \mathbf{R}^{n \times n} \rightarrow \mathbf{R}^{n \times n}$, the vector of body loads $\mathbf{f} : \mathbf{R} \rightarrow \mathbf{R}^n$, and a displacement-dependent source term $g : \mathbf{R}^n \rightarrow \mathbf{R}$. For the load, source, and diffusivity functions we will require uniform boundedness and Lipschitz continuity, that is there exist positive constants $f_1, f_2, L_f, g_1, g_2, L_g$, and $\vartheta_1, \vartheta_2, L_\vartheta$, such that

$$f_1 \leq |\mathbf{f}(s)| \leq f_2, \quad |\mathbf{f}(s) - \mathbf{f}(t)| \leq L_f |s - t| \quad \forall s, t \in \mathbf{R}, \quad (2.5)$$

$$g_1 \leq g(\mathbf{w}) \leq g_2, \quad |g(\mathbf{v}) - g(\mathbf{w})| \leq L_g |\mathbf{v} - \mathbf{w}| \quad \forall \mathbf{v}, \mathbf{w} \in \mathbf{R}^n, \quad (2.6)$$

$$\vartheta_1 \leq |\vartheta(\boldsymbol{\tau})| \leq \vartheta_2, \quad |\vartheta(\boldsymbol{\tau}) - \vartheta(\boldsymbol{\zeta})| \leq L_\vartheta |\boldsymbol{\tau} - \boldsymbol{\zeta}| \quad \forall \boldsymbol{\tau}, \boldsymbol{\zeta} \in \mathbf{R}^{n \times n}. \quad (2.7)$$

Additionally, ϑ is of class C^1 and uniformly positive definite, the latter meaning that there exists $\vartheta_0 > 0$ such that

$$\vartheta(\boldsymbol{\tau}) \mathbf{w} \cdot \mathbf{w} \geq \vartheta_0 |\mathbf{w}|^2 \quad \forall \mathbf{w} \in \mathbf{R}^n, \quad \forall \boldsymbol{\tau} \in \mathbf{R}^{n \times n}. \quad (2.8)$$

Finally, we assume that $\mathbf{f}(\phi) \in \mathbf{H}^1(\Omega)$ for each $\phi \in H^1(\Omega)$, and that for each $\gamma \in (0, 1)$ there exists a constant $C_\gamma > 0$ such that $g(\mathbf{w}) \in H^\gamma(\Omega)$ for each $\mathbf{w} \in H^\gamma(\Omega)$ and

$$\|g(\mathbf{w})\|_{\gamma, \Omega} \leq C_\gamma \|\mathbf{w}\|_{\gamma, \Omega}. \quad (2.9)$$

Examples of stress-dependent diffusivity functions and concentration-dependent body loads, though not all of them satisfying each one of the above described hypotheses, may include exponential functions of the volumetric stress for lithiation of batteries [22], simple polynomial relationships for biological materials [12], or Carreau-type laws for ϑ , that is

$$\vartheta(\boldsymbol{\sigma}) = C_0 \exp(-\text{tr } \boldsymbol{\sigma}) \mathbb{I}, \quad \vartheta(\boldsymbol{\sigma}) = C_0 \mathbb{I} + C_1 \boldsymbol{\sigma} + C_2 \boldsymbol{\sigma}^2, \quad \vartheta(\boldsymbol{\sigma}) = (C_0 + C_1(1 - |\boldsymbol{\sigma}|^2)^{-1/2}) \mathbb{I},$$

respectively, where C_0, C_1, C_2 are constants, whereas for \mathbf{f} linear dependences modelling isotropic swelling in composite materials [23], saturation-based descriptions for viscous layers [37], or concentration gradient modulations for single-cell mechanics [33] are considered, that is

$$\mathbf{f}(\phi) = \mathbf{C} \phi, \quad \mathbf{f}(\phi) = \mathbf{C}(1 - \phi)^{m-1}, \quad \mathbf{f}(\phi) = C_0 \nabla \phi,$$

respectively, where $\mathbf{C} \in \mathbf{R}^n$ and $m > 1$.

3 Weak formulation and solvability analysis

In this section we derive an augmented fully-mixed variational formulation for (2.1)-(2.4) and propose a fixed-point strategy for its analysis. We show that the fixed-point operator is well-defined and apply the Schauder's theorem to prove existence of solution, whereas Banach fixed-point theorem will lead to uniqueness of solution under small data assumptions.

3.1 The mixed-mixed formulation

According to the zero tractions imposed on Σ and Γ (*cf.* second relations of (2.3)), we introduce the spaces

$$\mathbb{H}_\Sigma(\mathbf{div}; \Omega) := \left\{ \boldsymbol{\tau} \in \mathbb{H}(\mathbf{div}; \Omega) : \boldsymbol{\tau} \boldsymbol{\nu} = \mathbf{0} \quad \text{on } \Sigma \right\}$$

and

$$\mathbf{H}_\Gamma(\mathbf{div}; \Omega) := \left\{ \tilde{\boldsymbol{\tau}} \in \mathbf{H}(\mathbf{div}; \Omega) : \tilde{\boldsymbol{\tau}} \cdot \boldsymbol{\nu} = 0 \quad \text{on } \Gamma \right\}.$$

Then we define the space of skew-symmetric tensors

$$\mathbb{L}_{\text{skew}}^2(\Omega) := \{ \boldsymbol{\eta} \in \mathbb{L}^2(\Omega) : \boldsymbol{\eta} + \boldsymbol{\eta}^t = 0 \},$$

and apply the Dirichlet boundary condition for displacements (first relation of (2.3)) to write the elasticity problem in weak form: find $(\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho})) \in \mathbf{H}_1 := \mathbb{H}_\Sigma(\mathbf{div}; \Omega) \times (\mathbf{L}^2(\Omega) \times \mathbb{L}_{\text{skew}}^2(\Omega))$ such that

$$\begin{aligned} a(\boldsymbol{\sigma}, \boldsymbol{\tau}) + b(\boldsymbol{\tau}, (\mathbf{u}, \boldsymbol{\rho})) &= G(\boldsymbol{\tau}) \quad \forall \boldsymbol{\tau} \in \mathbb{H}_\Sigma(\mathbf{div}; \Omega), \\ b(\boldsymbol{\sigma}, (\mathbf{v}, \boldsymbol{\eta})) &= F_\phi(\mathbf{v}, \boldsymbol{\eta}) \quad \forall (\mathbf{v}, \boldsymbol{\eta}) \in \mathbf{L}^2(\Omega) \times \mathbb{L}_{\text{skew}}^2(\Omega), \end{aligned} \quad (3.1)$$

where $a : \mathbb{H}_\Sigma(\mathbf{div}; \Omega) \times \mathbb{H}_\Sigma(\mathbf{div}; \Omega) \rightarrow \mathbb{R}$ and $b : \mathbb{H}_\Sigma(\mathbf{div}; \Omega) \times (\mathbf{L}^2(\Omega) \times \mathbb{L}_{\text{skew}}^2(\Omega)) \rightarrow \mathbb{R}$ are bilinear forms defined as

$$a(\boldsymbol{\zeta}, \boldsymbol{\tau}) = \frac{1}{2\mu} \int_\Omega \boldsymbol{\zeta} : \boldsymbol{\tau} - \frac{\lambda}{2\mu(n\lambda + 2\mu)} \int_\Omega \text{tr}(\boldsymbol{\zeta}) \text{tr}(\boldsymbol{\tau}), \quad b(\boldsymbol{\tau}, (\mathbf{v}, \boldsymbol{\eta})) := \int_\Omega \mathbf{v} \cdot \mathbf{div} \boldsymbol{\tau} + \int_\Omega \boldsymbol{\eta} : \boldsymbol{\tau},$$

for $\boldsymbol{\zeta}, \boldsymbol{\tau} \in \mathbb{H}_\Sigma(\mathbf{div}; \Omega)$ and $(\mathbf{v}, \boldsymbol{\eta}) \in \mathbf{L}^2(\Omega) \times \mathbb{L}_{\text{skew}}^2(\Omega)$. In turn, the functionals $F_\phi \in \mathbb{H}(\mathbf{div}; \Omega)'$ and $G \in (\mathbf{L}^2(\Omega) \times \mathbb{L}_{\text{skew}}^2(\Omega))'$ are given by

$$G(\boldsymbol{\tau}) := \langle \boldsymbol{\tau} \boldsymbol{\nu}, \mathbf{u}_D \rangle_\Gamma \quad \text{and} \quad F_\phi(\mathbf{v}, \boldsymbol{\eta}) := - \int_\Omega \mathbf{f}(\phi) \cdot \mathbf{v}, \quad (3.2)$$

for $(\boldsymbol{\tau}, (\mathbf{v}, \boldsymbol{\eta})) \in \mathbf{H}_1$, where $\langle \cdot, \cdot \rangle_\Gamma$ stands for the duality pairing of $\mathbf{H}^{-1/2}(\Gamma)$ and $\mathbf{H}^{1/2}(\Gamma)$.

In turn, defining the concentration gradient $\mathbf{t} := \nabla \phi$, we can recast the diffusion equation as

$$\begin{aligned} \tilde{\boldsymbol{\sigma}} &= \vartheta(\boldsymbol{\sigma}) \mathbf{t} \quad \text{in } \Omega, \quad \mathbf{t} = \nabla \phi \quad \text{in } \Omega, \quad -\text{div} \tilde{\boldsymbol{\sigma}} = g(\mathbf{u}) \quad \text{in } \Omega, \\ \phi &= \phi_D \quad \text{on } \Sigma \quad \text{and} \quad \tilde{\boldsymbol{\sigma}} \cdot \boldsymbol{\nu} = 0 \quad \text{on } \Gamma. \end{aligned} \quad (3.3)$$

We then test the three-field problem (3.3) against $\mathbf{s} \in \mathbf{L}^2(\Omega)$, $\tilde{\boldsymbol{\tau}} \in \mathbf{H}_\Gamma(\mathbf{div}; \Omega)$ and $\psi \in L^2(\Omega)$. Integrating by parts the expression $\int_\Omega \nabla \phi \cdot \tilde{\boldsymbol{\tau}}$ and using the Dirichlet boundary condition for ϕ (2.4), we arrive at the weak formulation: find $(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) \in \mathbf{L}^2(\Omega) \times \mathbf{H}_\Gamma(\mathbf{div}; \Omega) \times L^2(\Omega)$ such that

$$\begin{aligned} \int_\Omega \vartheta(\boldsymbol{\sigma}) \mathbf{t} \cdot \mathbf{s} - \int_\Omega \tilde{\boldsymbol{\sigma}} \cdot \mathbf{s} &= 0 \quad \forall \mathbf{s} \in \mathbf{L}^2(\Omega), \\ \int_\Omega \tilde{\boldsymbol{\tau}} \cdot \mathbf{t} + \int_\Omega \phi \text{div} \tilde{\boldsymbol{\tau}} &= \langle \tilde{\boldsymbol{\tau}} \cdot \boldsymbol{\nu}, \phi_D \rangle_\Sigma \quad \forall \tilde{\boldsymbol{\tau}} \in \mathbf{H}_\Gamma(\mathbf{div}; \Omega), \\ - \int_\Omega \psi \text{div} \tilde{\boldsymbol{\sigma}} &= \int_\Omega \psi g(\mathbf{u}) \quad \forall \psi \in L^2(\Omega). \end{aligned} \quad (3.4)$$

In view of modifying the regularity properties of the coupled problem, we proceed to enrich the foregoing equations with the following residual terms:

$$\begin{aligned}
\kappa_1 \int_{\Omega} \{\tilde{\boldsymbol{\sigma}} - \vartheta(\boldsymbol{\sigma}) \mathbf{t}\} \cdot \tilde{\boldsymbol{\tau}} &= 0 & \forall \tilde{\boldsymbol{\tau}} \in \mathbf{H}_{\Gamma}(\text{div}; \Omega), \\
\kappa_2 \int_{\Omega} \text{div } \tilde{\boldsymbol{\sigma}} \text{ div } \tilde{\boldsymbol{\tau}} &= -\kappa_2 \int_{\Omega} g(\mathbf{u}) \text{ div } \tilde{\boldsymbol{\tau}} & \forall \tilde{\boldsymbol{\tau}} \in \mathbf{H}_{\Gamma}(\text{div}; \Omega), \\
\kappa_3 \int_{\Omega} \{\nabla \phi - \mathbf{t}\} \cdot \nabla \psi &= 0 & \forall \psi \in H^1(\Omega), \\
\kappa_4 \int_{\Sigma} \phi \psi &= \kappa_4 \int_{\Sigma} \phi_{\text{D}} \psi & \forall \psi \in H^1(\Omega),
\end{aligned} \tag{3.5}$$

where $\kappa_1, \kappa_2, \kappa_3$ and κ_4 are positive parameters to be specified later on. We remark that the identities required in (3.5) are nothing but the constitutive and the equilibrium equations concerning $\tilde{\boldsymbol{\sigma}}$, along with the relation defining \mathbf{t} , and the Dirichlet boundary condition for ϕ ; all of them tested differently from (3.4). Instead of (3.4), we will now focus on the following augmented formulation for the diffusion problem: find $(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) \in \mathbf{H}_2 := \mathbf{L}^2(\Omega) \times \mathbf{H}_{\Gamma}(\text{div}; \Omega) \times H^1(\Omega)$ such that

$$A_{\boldsymbol{\sigma}}((\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi), (\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi)) = G_{\mathbf{u}}(\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi) \quad \forall (\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi) \in \mathbf{H}_2, \tag{3.6}$$

where

$$\begin{aligned}
A_{\boldsymbol{\sigma}}((\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi), (\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi)) &:= \int_{\Omega} \vartheta(\boldsymbol{\sigma}) \mathbf{t} \cdot \mathbf{s} - \int_{\Omega} \tilde{\boldsymbol{\sigma}} \cdot \mathbf{s} + \int_{\Omega} \tilde{\boldsymbol{\tau}} \cdot \mathbf{t} + \int_{\Omega} \phi \text{ div } \tilde{\boldsymbol{\tau}} - \int_{\Omega} \psi \text{ div } \tilde{\boldsymbol{\sigma}} \\
&+ \kappa_1 \int_{\Omega} \{\tilde{\boldsymbol{\sigma}} - \vartheta(\boldsymbol{\sigma}) \mathbf{t}\} \cdot \tilde{\boldsymbol{\tau}} + \kappa_2 \int_{\Omega} \text{div } \tilde{\boldsymbol{\sigma}} \text{ div } \tilde{\boldsymbol{\tau}} + \kappa_3 \int_{\Omega} \{\nabla \phi - \mathbf{t}\} \cdot \nabla \psi + \kappa_4 \int_{\Sigma} \phi \psi,
\end{aligned} \tag{3.7}$$

and

$$G_{\mathbf{u}}(\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi) := \langle \tilde{\boldsymbol{\tau}} \cdot \boldsymbol{\nu}, \phi_{\text{D}} \rangle_{\Sigma} + \int_{\Omega} \psi g(\mathbf{u}) - \kappa_2 \int_{\Omega} g(\mathbf{u}) \text{ div } \tilde{\boldsymbol{\tau}} + \kappa_4 \int_{\Sigma} \phi_{\text{D}} \psi. \tag{3.8}$$

Consequently, we arrive at the following augmented fully-mixed formulation for (2.1)-(2.4): find $((\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho})), (\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi)) \in \mathbf{H}_1 \times \mathbf{H}_2$, such that

$$\begin{aligned}
a(\boldsymbol{\sigma}, \boldsymbol{\tau}) + b(\boldsymbol{\tau}, (\mathbf{u}, \boldsymbol{\rho})) &= G(\boldsymbol{\tau}) & \forall \boldsymbol{\tau} \in \mathbb{H}_{\Sigma}(\mathbf{div}; \Omega), \\
b(\boldsymbol{\sigma}, (\mathbf{v}, \boldsymbol{\eta})) &= F_{\phi}(\mathbf{v}, \boldsymbol{\eta}) & \forall (\mathbf{v}, \boldsymbol{\eta}) \in \mathbf{L}^2(\Omega) \times \mathbb{L}_{\text{skew}}^2(\Omega), \\
A_{\boldsymbol{\sigma}}((\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi), (\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi)) &= G_{\mathbf{u}}(\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi) & \forall (\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi) \in \mathbf{H}_2.
\end{aligned} \tag{3.9}$$

3.2 A fixed-point approach

Here we utilize a fixed-point strategy to prove that problem (3.9) is well-posed. Let us first define the operator $\mathbf{S} : H^1(\Omega) \rightarrow \mathbf{H}_1$ as

$$\mathbf{S}(\phi) := (\mathbf{S}_1(\phi), (\mathbf{S}_2(\phi), \mathbf{S}_3(\phi))) := (\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho})) \quad \forall \phi \in H^1(\Omega),$$

where $(\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho}))$ is the unique solution of (3.1) with the given ϕ . In turn, we define the operator $\tilde{\mathbf{S}} : \mathbb{H}_{\Sigma}(\mathbf{div}; \Omega) \times \mathbf{L}^2(\Omega) \rightarrow \mathbf{H}_2$ as

$$\tilde{\mathbf{S}}(\boldsymbol{\sigma}, \mathbf{u}) := (\tilde{\mathbf{S}}_1(\boldsymbol{\sigma}, \mathbf{u}), \tilde{\mathbf{S}}_2(\boldsymbol{\sigma}, \mathbf{u}), \tilde{\mathbf{S}}_3(\boldsymbol{\sigma}, \mathbf{u})) := (\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) \quad \forall (\boldsymbol{\sigma}, \mathbf{u}) \in \mathbb{H}_{\Sigma}(\mathbf{div}; \Omega) \times \mathbf{L}^2(\Omega),$$

where $(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi)$ is the unique solution of (3.6) with the given $(\boldsymbol{\sigma}, \mathbf{u})$. In this way, by introducing the operator $\mathbf{T} : H^1(\Omega) \rightarrow H^1(\Omega)$ as

$$\mathbf{T}(\phi) := \tilde{\mathbf{S}}_3(\mathbf{S}_1(\phi), \mathbf{S}_2(\phi)) \quad \forall \phi \in H^1(\Omega),$$

we realize that (3.9) can be rewritten as the fixed-point problem: find $\phi \in H^1(\Omega)$ such that

$$\mathbf{T}(\phi) = \phi. \quad (3.10)$$

However, we remark in advance that the definition of \mathbf{T} will be only in a closed ball of $H^1(\Omega)$.

In order to analyze the well-posedness of (3.1) and (3.6), we recall from [10] that

$$\mathbb{H}(\mathbf{div}; \Omega) = \mathbb{H}_0(\mathbf{div}; \Omega) \oplus \mathbb{R}\mathbb{I}, \quad \text{with} \quad \mathbb{H}_0(\mathbf{div}; \Omega) := \left\{ \boldsymbol{\tau} \in \mathbb{H}(\mathbf{div}; \Omega) : \int_{\Omega} \text{tr}(\boldsymbol{\tau}) = 0 \right\},$$

which means that for each $\boldsymbol{\tau} \in \mathbb{H}(\mathbf{div}; \Omega)$ there exist unique

$$\boldsymbol{\tau}_0 := \boldsymbol{\tau} - \left\{ \frac{1}{n|\Omega|} \int_{\Omega} \text{tr}(\boldsymbol{\tau}) \right\} \mathbb{I} \in \mathbb{H}_0(\mathbf{div}; \Omega) \quad \text{and} \quad d := \frac{1}{n|\Omega|} \int_{\Omega} \text{tr}(\boldsymbol{\tau}) \in \mathbb{R},$$

such that $\boldsymbol{\tau} = \boldsymbol{\tau}_0 + d\mathbb{I}$. We also collect the following three technical lemmas, whose proofs can be found in [10, Prop. 3.1], [17, Lemma 2.2], and [14, Lemma 3.3], respectively.

Lemma 3.1 *There exists $c_1 > 0$ such that*

$$c_1 \|\boldsymbol{\tau}_0\|_{0,\Omega}^2 \leq \|\boldsymbol{\tau}^d\|_{0,\Omega}^2 + \|\mathbf{div} \boldsymbol{\tau}\|_{0,\Omega}^2 \quad \forall \boldsymbol{\tau} = \boldsymbol{\tau}_0 + c\mathbb{I} \in \mathbb{H}(\mathbf{div}; \Omega),$$

with $\boldsymbol{\tau}_0 \in \mathbb{H}_0(\mathbf{div}; \Omega)$ and $c \in \mathbb{R}$.

Lemma 3.2 *There exists $c_2 > 0$ such that*

$$c_2 \|\boldsymbol{\tau}\|_{\mathbf{div};\Omega}^2 \leq \|\boldsymbol{\tau}_0\|_{\mathbf{div};\Omega}^2 \quad \forall \boldsymbol{\tau} = \boldsymbol{\tau}_0 + c\mathbb{I} \in \mathbb{H}_{\Sigma}(\mathbf{div}; \Omega),$$

with $\boldsymbol{\tau}_0 \in \mathbb{H}_0(\mathbf{div}; \Omega)$ and $c \in \mathbb{R}$.

Lemma 3.3 *There exists $c_3 > 0$ such that*

$$|\psi|_{1,\Omega}^2 + \|\psi\|_{0,\Sigma}^2 \geq c_3 \|\psi\|_{1,\Omega}^2 \quad \forall \psi \in H^1(\Omega).$$

In what follows we show that \mathbf{T} has at least one fixed point. Firstly we will prove that the uncoupled problems defined by \mathbf{S} and $\tilde{\mathbf{S}}$ are well-posed, where we emphasize that \mathbf{S} is defined similarly as in [18], and therefore we omit parts of the proofs whenever necessary. Our analysis will focus on the uncoupled problem (3.6) and its repercussion on \mathbf{T} . Let us start by recalling the continuity of a and b :

$$|a(\boldsymbol{\zeta}, \boldsymbol{\tau})| \leq \frac{1}{\mu} \|\boldsymbol{\zeta}\|_{\mathbf{div};\Omega} \|\boldsymbol{\tau}\|_{\mathbf{div};\Omega} \quad \forall \boldsymbol{\zeta}, \boldsymbol{\tau} \in \mathbb{H}_{\Sigma}(\mathbf{div}; \Omega), \quad (3.11)$$

$$|b(\boldsymbol{\tau}, (\mathbf{v}, \boldsymbol{\eta}))| \leq \|\boldsymbol{\tau}\|_{\mathbf{div};\Omega} \|(\mathbf{v}, \boldsymbol{\eta})\| \quad \forall \boldsymbol{\tau} \in \mathbb{H}_{\Sigma}(\mathbf{div}; \Omega), \quad \forall (\mathbf{v}, \boldsymbol{\eta}) \in \mathbf{L}^2(\Omega) \times \mathbb{L}_{\text{skew}}^2(\Omega).$$

Furthermore, it is not difficult to see that a is strongly elliptic in the kernel of b . In fact, we denote the operator induced by the bilinear form b as \mathbf{B} , and note that

$$V := N(\mathbf{B}) = \left\{ \boldsymbol{\tau} \in \mathbb{H}_{\Sigma}(\mathbf{div}; \Omega) : \mathbf{div} \boldsymbol{\tau} = 0 \text{ in } \Omega, \quad \boldsymbol{\tau} = \boldsymbol{\tau}^t \text{ in } \Omega \right\},$$

from which, we deduce that

$$a(\boldsymbol{\tau}, \boldsymbol{\tau}) \geq \frac{1}{2\mu} \|\boldsymbol{\tau}^d\|_{0,\Omega}^2 \geq \frac{c_1 c_2}{2\mu} \|\boldsymbol{\tau}\|_{0,\Omega}^2 = \alpha \|\boldsymbol{\tau}\|_{\mathbf{div};\Omega}^2 \quad \forall \boldsymbol{\tau} \in V, \quad (3.12)$$

where c_1 and c_2 are the constants provided by Lemmas 3.1 and 3.2, respectively. Additionally, as a slight modification of the proof of [16, Section 2.4.3], we find that \mathbf{B} is surjective. Finally, we observe that G and F_{ϕ} are bounded with

$$\|G\| \leq \|\mathbf{u}_D\|_{1/2,\Gamma} \quad \text{and} \quad \|F_{\phi}\| \leq f_2 |\Omega|^{1/2}. \quad (3.13)$$

This analysis confirms the well-posedness of (3.1), which is abridged in the following lemma.

Lemma 3.4 For each $\phi \in \mathbf{H}^1(\Omega)$ the problem (3.1) has a unique solution $\mathbf{S}(\phi) := (\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho})) \in \mathbf{H}_1$. Moreover, there exists $c_{\mathbf{S}} > 0$, independent of ϕ , such that

$$\|\mathbf{S}(\phi)\|_{\mathbf{H}_1} = \|(\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho}))\|_{\mathbf{H}_1} \leq c_{\mathbf{S}} \left\{ \|\mathbf{u}_D\|_{1/2, \Gamma} + f_2 |\Omega|^{1/2} \right\}. \quad (3.14)$$

Proof. It follows from estimates (3.11)–(3.13) and a direct application of the Babuška-Brezzi theory (see, e.g. [16], Thm. 2.3). We refer to [18, Lemma 2.2] for further details. \square

In turn, we prove the well-posedness of problem (3.6) with the next result.

Lemma 3.5 Assume that $\kappa_1 \in \left(0, \frac{2\delta\vartheta_0}{\vartheta_2}\right)$ and $\kappa_3 \in \left(0, 2\tilde{\delta}\left(\vartheta_0 - \frac{\kappa_1\vartheta_2}{2\delta}\right)\right)$ with $\delta \in \left(0, \frac{2}{\vartheta_2}\right)$, $\tilde{\delta} \in (0, 2)$, and $\kappa_2, \kappa_4 > 0$. Then, for each $(\boldsymbol{\sigma}, \mathbf{u}) \in \mathbb{H}_{\Sigma}(\mathbf{div}; \Omega) \times \mathbf{L}^2(\Omega)$, problem (3.6) has a unique solution $\tilde{\mathbf{S}}(\boldsymbol{\sigma}, \mathbf{u}) = (\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) \in \mathbf{H}_2$. Moreover, there exists $\tilde{c}_{\mathbf{S}} > 0$, independent of $(\boldsymbol{\sigma}, \mathbf{u})$, such that

$$\|\tilde{\mathbf{S}}(\boldsymbol{\sigma}, \mathbf{u})\|_{\mathbf{H}_2} = \|(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi)\|_{\mathbf{H}_2} \leq \tilde{c}_{\mathbf{S}} \left\{ \|\phi_D\|_{1/2, \Sigma} + g_2 |\Omega|^{1/2} \right\}. \quad (3.15)$$

Proof. Firstly, we note from (3.7) that $A_{\boldsymbol{\sigma}}$ is a bilinear form. Next, applying Cauchy-Schwarz's inequality, the lower bound for ϑ (cf. 2.7), and the trace theorem (with constant c_0), we find that

$$\begin{aligned} |A_{\boldsymbol{\sigma}}((\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi), (\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi))| &\leq \vartheta_2 \|\mathbf{t}\|_{0, \Omega} \|\mathbf{s}\|_{0, \Omega} + \|\tilde{\boldsymbol{\sigma}}\|_{0, \Omega} \|\mathbf{s}\|_{0, \Omega} + \|\tilde{\boldsymbol{\tau}}\|_{0, \Omega} \|\mathbf{t}\|_{0, \Omega} \\ &\quad + \|\phi\|_{0, \Omega} \|\operatorname{div} \tilde{\boldsymbol{\tau}}\|_{0, \Omega} + \|\psi\|_{0, \Omega} \|\operatorname{div} \tilde{\boldsymbol{\sigma}}\|_{0, \Omega} + \kappa_1 \|\tilde{\boldsymbol{\sigma}}\|_{0, \Omega} \|\tilde{\boldsymbol{\tau}}\|_{0, \Omega} + \kappa_1 \vartheta_2 \|\mathbf{t}\|_{0, \Omega} \|\tilde{\boldsymbol{\tau}}\|_{0, \Omega} \\ &\quad + \kappa_2 \|\operatorname{div} \tilde{\boldsymbol{\sigma}}\|_{0, \Omega} \|\operatorname{div} \tilde{\boldsymbol{\tau}}\|_{0, \Omega} + \kappa_3 |\phi|_{1, \Omega} |\psi|_{1, \Omega} + \kappa_3 \|\mathbf{t}\|_{0, \Omega} |\psi|_{1, \Omega} + c_0^2 \kappa_4 \|\phi\|_{1, \Omega} \|\psi\|_{1, \Omega}. \end{aligned}$$

It follows that there exists a positive constant $\|A\|$, depending on $\vartheta_2, c_0, \kappa_1, \kappa_2, \kappa_3$ and κ_4 , such that

$$|A_{\boldsymbol{\sigma}}((\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi), (\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi))| \leq \|A\| \|(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi)\|_{\mathbf{H}_2} \|(\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi)\|_{\mathbf{H}_2} \quad \forall (\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi), (\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi) \in \mathbf{H}_2, \quad (3.16)$$

and hence $A_{\boldsymbol{\sigma}}$ is bounded independently of $(\boldsymbol{\sigma}, \mathbf{u}) \in \mathbb{H}_{\Sigma}(\mathbf{div}; \Omega) \times \mathbf{L}^2(\Omega)$. In turn, we now aim to show that $A_{\boldsymbol{\sigma}}$ is \mathbf{H}_2 -elliptic. To this end, given $(\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi) \in \mathbf{H}_2$, we apply (2.8) and find that

$$\begin{aligned} A_{\boldsymbol{\sigma}}((\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi), (\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi)) &\geq \int_{\Omega} \vartheta(\boldsymbol{\sigma}) \mathbf{s} \cdot \mathbf{s} + \kappa_1 \|\tilde{\boldsymbol{\tau}}\|_{0, \Omega}^2 - \kappa_1 \vartheta_2 \|\mathbf{s}\|_{0, \Omega} \|\tilde{\boldsymbol{\tau}}\|_{0, \Omega} + \kappa_2 \|\operatorname{div} \tilde{\boldsymbol{\tau}}\|_{0, \Omega}^2 \\ &\quad + \kappa_3 |\psi|_{1, \Omega}^2 - \kappa_3 \|\mathbf{s}\|_{0, \Omega} |\psi|_{1, \Omega} + \kappa_4 \|\psi\|_{0, \Sigma}^2 \\ &\geq \vartheta_0 \|\mathbf{s}\|_{0, \Omega}^2 + \kappa_1 \|\tilde{\boldsymbol{\tau}}\|_{0, \Omega}^2 + \kappa_2 \|\operatorname{div} \tilde{\boldsymbol{\tau}}\|_{0, \Omega}^2 - \frac{\kappa_1 \vartheta_2}{2\delta} \|\mathbf{s}\|_{0, \Omega}^2 - \frac{\kappa_1 \vartheta_2 \delta}{2} \|\tilde{\boldsymbol{\tau}}\|_{0, \Omega}^2 \\ &\quad + \kappa_3 |\psi|_{1, \Omega}^2 - \frac{\kappa_3}{2\tilde{\delta}} \|\mathbf{s}\|_{0, \Omega}^2 - \frac{\kappa_3 \tilde{\delta}}{2} |\psi|_{1, \Omega}^2 + \kappa_4 \|\psi\|_{0, \Sigma}^2 \\ &= \left\{ \left(\vartheta_0 - \frac{\kappa_1 \vartheta_2}{2\delta} \right) - \frac{\kappa_3}{2\tilde{\delta}} \right\} \|\mathbf{s}\|_{0, \Omega}^2 + \kappa_1 \left(1 - \frac{\vartheta_2 \delta}{2} \right) \|\tilde{\boldsymbol{\tau}}\|_{0, \Omega}^2 + \kappa_2 \|\operatorname{div} \tilde{\boldsymbol{\tau}}\|_{0, \Omega}^2 \\ &\quad + \kappa_3 \left(1 - \frac{\tilde{\delta}}{2} \right) |\psi|_{1, \Omega}^2 + \kappa_4 \|\psi\|_{0, \Sigma}^2. \end{aligned} \quad (3.17)$$

Then, assuming the stipulated hypotheses on $\delta, \tilde{\delta}, \kappa_1, \kappa_2, \kappa_3, \kappa_4$ and applying Lemma 3.3, we can define

$$\tilde{\alpha}_1 := \left\{ \left(\vartheta_0 - \frac{\kappa_1 \vartheta_2}{2\delta} \right) - \frac{\kappa_3}{2\tilde{\delta}} \right\}, \quad \tilde{\alpha}_2 := \min \left\{ \kappa_1 \left(1 - \frac{\vartheta_2 \delta}{2} \right), \kappa_2 \right\}, \quad \tilde{\alpha}_3 := c_3 \min \left\{ \kappa_3 \left(1 - \frac{\tilde{\delta}}{2} \right), \kappa_4 \right\},$$

which allows us to deduce from (3.17) that

$$A_{\boldsymbol{\sigma}}((\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi), (\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi)) \geq \tilde{\alpha} \|(\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi)\|^2 \quad \forall (\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi) \in \mathbf{H}_2, \quad (3.18)$$

where $\tilde{\alpha} := \min \{\tilde{\alpha}_1, \tilde{\alpha}_2, \tilde{\alpha}_3\}$ is the ellipticity constant of $A_{\boldsymbol{\sigma}}$. Next, applying Cauchy-Schwarz's inequality and the trace estimates in $\mathbb{H}(\mathbf{div}; \Omega)$ and $\mathbf{H}^1(\Omega)$, with constants 1 and c_0 , respectively, to (3.8), we find that there exists a positive constant $\|\tilde{G}\|$ depending on κ_2, κ_3 and c_0 , such that

$$\|G_{\mathbf{u}}\| \leq \|\tilde{G}\| \left\{ \|\phi_{\mathbf{D}}\|_{1/2, \Sigma} + g_2 |\Omega|^{1/2} \right\}. \quad (3.19)$$

Finally, a direct application of the Lax-Milgram lemma proves that for each $(\boldsymbol{\sigma}, \mathbf{u}) \in \mathbb{H}_{\Sigma}(\mathbf{div}; \Omega) \times \mathbf{L}^2(\Omega)$, problem (3.6) has a unique solution $\tilde{\mathbf{S}}(\boldsymbol{\sigma}, \mathbf{u}) = (\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) \in \mathbf{H}_2$. Moreover, a continuous dependence result is given by

$$\|\tilde{\mathbf{S}}(\boldsymbol{\sigma}, \mathbf{u})\|_{\mathbf{H}_2} = \|(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi)\|_{\mathbf{H}_2} \leq \frac{1}{\tilde{\alpha}} \|G_{\mathbf{u}}\|_{\mathbf{H}_2} \leq \tilde{c}_{\mathbf{S}} \left\{ \|\phi_{\mathbf{D}}\|_{1/2, \Sigma} + g_2 |\Omega|^{1/2} \right\},$$

where $\tilde{c}_{\mathbf{S}} := \frac{\|\tilde{G}\|}{\tilde{\alpha}}$, completing the proof. \square

Note that the constant $\tilde{\alpha}$ yielding ellipticity of $A_{\boldsymbol{\sigma}}$ can be maximized by choosing the parameters $\delta, \tilde{\delta}, \kappa_1$, and κ_3 as the middle points of their feasible ranges, and by taking κ_2 and κ_4 so that they maximize the minima defining $\tilde{\alpha}_2$ and $\tilde{\alpha}_3$, respectively. Adequate choices are then

$$\begin{aligned} \delta &= \frac{1}{\vartheta_2}, \quad \kappa_1 = \frac{\delta \vartheta_0}{\vartheta_2} = \frac{\vartheta_0}{\vartheta_2^2}, \quad \tilde{\delta} = 1, \quad \kappa_3 = \tilde{\delta} \left(\vartheta_0 - \frac{\kappa_1 \vartheta_2}{2\delta} \right) = \frac{\vartheta_0}{2}, \\ \kappa_2 &= \kappa_1 \left(1 - \frac{\delta \vartheta_2}{2} \right) = \frac{\vartheta_0}{2\vartheta_2^2}, \quad \kappa_4 = \kappa_3 \left(1 - \frac{\tilde{\delta}}{2} \right) = \frac{\vartheta_0}{4}, \end{aligned} \quad (3.20)$$

which yields

$$\tilde{\alpha}_1 = \frac{\vartheta_0}{4}, \quad \tilde{\alpha}_2 = \frac{\vartheta_0}{2\vartheta_2^2}, \quad \tilde{\alpha}_3 = c_3 \frac{\vartheta_0}{4}, \quad \text{and} \quad \tilde{\alpha} = \min \left\{ \min \{c_3, 1\} \frac{\vartheta_0}{4}, \frac{\vartheta_0}{2\vartheta_2^2} \right\}.$$

We end this section by introducing suitable regularity estimates on \mathbf{S} and $\tilde{\mathbf{S}}$, exactly as in [18, Section 2.2]. In fact, we concentrate in the case where Ω is a convex polygonal domain and $n = 2$, recall that $\mathbf{f}(\psi) \in \mathbf{H}^1(\Omega)$ for each $\psi \in \mathbf{H}^1(\Omega)$, and assume from now on that $\mathbf{u}_{\mathbf{D}} \in \mathbf{H}^{3/2+\gamma}(\Gamma)$, where γ is the positive constant whose existence is guaranteed in [9]. Then, applying precisely the estimate given in [9, eq. (3.9)] and recalling from the constitutive equation that the regularities of the unknowns are connected, we find that $\mathbf{S}(\psi) \in \mathbb{H}_{\Sigma}(\mathbf{div}; \Omega) \cap \mathbb{H}^{1+\gamma}(\Omega) \times \mathbf{H}^{2+\gamma}(\Omega) \times \mathbb{L}_{\text{skew}}^2(\Omega) \cap \mathbb{H}^{1+\gamma}(\Omega)$.

In turn, for $\tilde{\mathbf{S}}$ we note that, for a given pair $(\boldsymbol{\zeta}, \mathbf{w}) := (\mathbf{S}_1(\psi), \mathbf{S}_2(\psi)) \in \mathbb{H}_{\Sigma}(\mathbf{div}; \Omega) \cap \mathbb{H}^{1+\gamma}(\Omega) \times \mathbf{H}^{2+\gamma}(\Omega)$ (which denote the first and second components of the unique solution produced by the operator \mathbf{S}), the hypothesis given by relation (2.9) implies in particular that $g(\mathbf{w}) \in \mathbf{H}^{\gamma}(\Omega)$. Additionally, we assume that the coefficients $\vartheta(\boldsymbol{\zeta})_{ij}$ are in $C^{1+\gamma}(\bar{\Omega})$ and $\phi_{\mathbf{D}} \in \mathbf{H}^{3/2+\gamma}(\Sigma)$, then elliptic regularity results (cf. [21], [29]) guarantee that $\phi := \tilde{\mathbf{S}}_3(\boldsymbol{\zeta}, \mathbf{w}) \in \mathbf{H}^{2+\gamma}(\Omega)$, and therefore there exists $\tilde{C}_1 > 0$ such that

$$\|\tilde{\mathbf{S}}_1(\boldsymbol{\zeta}, \mathbf{w})\|_{1+\gamma, \Omega} = \|\mathbf{t}\|_{1+\gamma, \Omega} \leq \|\phi\|_{2+\gamma, \Omega} \leq \tilde{C}_1 \left\{ \|\phi_{\mathbf{D}}\|_{3/2+\gamma, \Sigma} + \|g(\mathbf{w})\|_{\gamma, \Omega} \right\}. \quad (3.21)$$

On the other hand, the Sobolev embedding theorem (cf. [24, Thm. A.5]) establishes the continuous injection $i_{\gamma} : \mathbf{H}^{1+\gamma}(\Omega) \rightarrow C^0(\bar{\Omega})$, with boundedness constant \tilde{C}_{γ} . Then, applying (3.21) implies that

$$\|\tilde{\mathbf{S}}_1(\boldsymbol{\zeta}, \mathbf{w})\|_{\infty, \Omega} = \|\mathbf{t}\|_{\infty, \Omega} \leq \tilde{C}_{\gamma} \|\mathbf{t}\|_{1+\gamma, \Omega} \leq \tilde{C}_{\gamma} \tilde{C}_1 \left\{ \|\phi_{\mathbf{D}}\|_{3/2+\gamma, \Sigma} + \|g(\mathbf{w})\|_{\gamma, \Omega} \right\}. \quad (3.22)$$

Finally, replacing the estimates (2.9) and (3.14) into (3.22), we find that

$$\|\tilde{\mathbf{S}}_1(\boldsymbol{\zeta}, \mathbf{w})\|_{\infty, \Omega} = \|\mathbf{t}\|_{\infty, \Omega} \leq C_{\infty} \left\{ \|\phi_{\mathbf{D}}\|_{3/2+\gamma, \Sigma} + \|\mathbf{u}_{\mathbf{D}}\|_{1/2, \Gamma} + f_2 |\Omega|^{1/2} \right\}, \quad (3.23)$$

where C_{∞} is a positive constant depending on C_{γ} , $c_{\mathbf{S}}$, \tilde{C}_{γ} and \tilde{C}_1 (cf. (2.9), (3.14), (3.21), (3.22)).

3.3 Solvability analysis of the fixed-point equation

We now verify the hypotheses of the Schauder fixed-point theorem (see, *eg.* [13, Thm. 3.7-1]). Before starting the result to be proved, we restrict \mathbf{T} to a ball and show that this operator maps into itself.

Lemma 3.6 *Let W be the closed and convex subset of $H^1(\Omega)$ defined by*

$$W := \left\{ \phi \in H^1(\Omega) : \|\phi\|_{1,\Omega} \leq \tilde{c}_{\mathbf{S}} \left\{ \|\phi_{\mathbf{D}}\|_{1/2,\Sigma} + g_2 |\Omega|^{1/2} \right\} \right\},$$

where $\tilde{c}_{\mathbf{S}}$ is the constant given by (3.14). Then $\mathbf{T}(W) \subseteq W$.

Proof. It suffices to recall the definition of \mathbf{T} and apply the estimate (3.15). \square

The following estimate is key to derive Lipschitz continuity of \mathbf{T} . For a proof see [18, Lemma 2.6].

Lemma 3.7 *There exists a positive constant $C_{\mathbf{S}}$ depending on μ, L_f, α (cf. (2.5), (3.12)) and the inf-sup constant of b , such that*

$$\|\mathbf{S}(\phi) - \mathbf{S}(\varphi)\|_{\mathbf{H}_1} \leq C_{\mathbf{S}} \|\phi - \varphi\|_{0,\Omega} \quad \forall \phi, \varphi \in H^1(\Omega). \quad (3.24)$$

We are in a position to establish the announced propertie of the operator \mathbf{T} .

Lemma 3.8 *Let $C_{\mathbf{S}}$ be the constant provided by Lemma 3.7. Then, for each $\phi, \varphi \in H^1(\Omega)$, there holds*

$$\|\mathbf{T}(\phi) - \mathbf{T}(\varphi)\|_{1,\Omega} \leq \frac{C_{\mathbf{S}}}{\tilde{\alpha}} \left\{ L_g (1 + \kappa_2^2)^{1/2} + L_{\vartheta} (1 + \kappa_1^2)^{1/2} \|\tilde{\mathbf{S}}_1(\mathbf{S}_1(\varphi), \mathbf{S}_2(\varphi))\|_{\infty,\Omega} \right\} \|\phi - \varphi\|_{0,\Omega}. \quad (3.25)$$

Proof. We begin by recalling that $\mathbf{T}(\phi) = \tilde{\mathbf{S}}_3(\mathbf{S}_1(\phi), \mathbf{S}_2(\phi))$ and $\mathbf{T}(\varphi) = \tilde{\mathbf{S}}_3(\mathbf{S}_1(\varphi), \mathbf{S}_2(\varphi)) \quad \forall \phi, \varphi \in H^1(\Omega)$. For notational purposes we rename

$$(\boldsymbol{\sigma}, \mathbf{u}) := (\mathbf{S}_1(\phi), \mathbf{S}_2(\phi)) \quad \text{and} \quad (\boldsymbol{\zeta}, \mathbf{w}) := (\mathbf{S}_1(\varphi), \mathbf{S}_2(\varphi)),$$

where $(\boldsymbol{\sigma}, \mathbf{u}), (\boldsymbol{\zeta}, \mathbf{w}) \in \mathbb{H}_{\Sigma}(\mathbf{div}; \Omega) \times \mathbf{L}^2(\Omega)$. Next, we consider $(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) := \tilde{\mathbf{S}}(\boldsymbol{\sigma}, \mathbf{u})$ and $(\mathbf{r}, \tilde{\boldsymbol{\zeta}}, \varphi) := \tilde{\mathbf{S}}(\boldsymbol{\zeta}, \mathbf{w})$, that is, for each $(\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi) \in \mathbf{H}_2$, one has

$$A_{\boldsymbol{\sigma}}((\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi), (\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi)) = G_{\mathbf{u}}(\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi) \quad \text{and} \quad A_{\boldsymbol{\zeta}}((\mathbf{r}, \tilde{\boldsymbol{\zeta}}, \varphi), (\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi)) = G_{\mathbf{w}}(\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi).$$

Analogously to the proof of [18, Lemma 2.7], we apply the ellipticity of $A_{\boldsymbol{\sigma}}$ (cf. (3.18)) and then, by adding and subtracting appropriate terms, we find that

$$\begin{aligned} & \tilde{\alpha} \|(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{r}, \tilde{\boldsymbol{\zeta}}, \varphi)\|_{\mathbf{H}_2}^2 \\ & \leq A_{\boldsymbol{\sigma}}((\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi), (\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{r}, \tilde{\boldsymbol{\zeta}}, \varphi)) - A_{\boldsymbol{\sigma}}((\mathbf{r}, \tilde{\boldsymbol{\zeta}}, \varphi), (\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{r}, \tilde{\boldsymbol{\zeta}}, \varphi)) \\ & = (G_{\mathbf{u}} - G_{\mathbf{w}})((\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{r}, \tilde{\boldsymbol{\zeta}}, \varphi)) + (A_{\boldsymbol{\zeta}} - A_{\boldsymbol{\sigma}})((\mathbf{r}, \tilde{\boldsymbol{\zeta}}, \varphi), (\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{r}, \tilde{\boldsymbol{\zeta}}, \varphi)). \end{aligned} \quad (3.26)$$

Using the definition of $A_{\boldsymbol{\sigma}}, G_{\mathbf{u}}$, Cauchy-Schwarz's inequality, and (2.6), (2.7), we can assert that

$$\begin{aligned} |(G_{\mathbf{u}} - G_{\mathbf{w}})((\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{r}, \tilde{\boldsymbol{\zeta}}, \varphi))| &= \left| \int_{\Omega} (g(\mathbf{u}) - g(\mathbf{w})) \left\{ (\phi - \varphi) - \kappa_2 \operatorname{div}(\tilde{\boldsymbol{\sigma}} - \tilde{\boldsymbol{\zeta}}) \right\} \right| \\ &\leq L_g \|\mathbf{u} - \mathbf{w}\|_{0,\Omega} \left\{ \|\phi - \varphi\|_{0,\Omega} + \kappa_2 \|\operatorname{div}(\tilde{\boldsymbol{\sigma}} - \tilde{\boldsymbol{\zeta}})\|_{0,\Omega} \right\} \\ &\leq L_g (1 + \kappa_2^2)^{1/2} \|\mathbf{u} - \mathbf{w}\|_{0,\Omega} \|(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{r}, \tilde{\boldsymbol{\zeta}}, \varphi)\|_{\mathbf{H}_2}, \end{aligned} \quad (3.27)$$

and

$$\begin{aligned}
|(A_\zeta - A_\sigma)((\mathbf{r}, \tilde{\zeta}, \varphi), (\mathbf{t}, \tilde{\sigma}, \phi) - (\mathbf{r}, \tilde{\zeta}, \varphi))| &= \left| \int_{\Omega} (\vartheta(\zeta) - \vartheta(\sigma)) \mathbf{r} \cdot \left\{ (\mathbf{t} - \mathbf{r}) - \kappa_1(\tilde{\sigma} - \tilde{\zeta}) \right\} \right| \\
&\leq L_\vartheta \|\sigma - \zeta\|_{0,\Omega} \|\mathbf{r}\|_{\infty,\Omega} \left\{ \|\mathbf{t} - \mathbf{r}\|_{0,\Omega} + \kappa_1 \|\tilde{\sigma} - \tilde{\zeta}\|_{0,\Omega} \right\}. \\
&\leq L_\vartheta (1 + \kappa_1^2)^{1/2} \|\sigma - \zeta\|_{0,\Omega} \|\mathbf{r}\|_{\infty,\Omega} \|(\mathbf{t}, \tilde{\sigma}, \phi) - (\mathbf{r}, \tilde{\zeta}, \varphi)\|_{\mathbf{H}_2},
\end{aligned} \tag{3.28}$$

whence the inequalities (3.26), (3.27) and (3.28) imply that

$$\|(\mathbf{t}, \tilde{\sigma}, \phi) - (\mathbf{r}, \tilde{\zeta}, \varphi)\|_{\mathbf{H}_2} \leq \frac{1}{\tilde{\alpha}} \left\{ L_g (1 + \kappa_2^2)^{1/2} \|\mathbf{u} - \mathbf{w}\|_{0,\Omega} + L_\vartheta (1 + \kappa_1^2)^{1/2} \|\sigma - \zeta\|_{0,\Omega} \|\mathbf{r}\|_{\infty,\Omega} \right\}. \tag{3.29}$$

Next, according to the definitions given when starting the proof, we can rewrite (3.29) as

$$\begin{aligned}
\|\tilde{\mathbf{S}}(\mathbf{S}_1(\phi), \mathbf{S}_2(\phi)) - \tilde{\mathbf{S}}(\mathbf{S}_1(\varphi), \mathbf{S}_2(\varphi))\|_{\mathbf{H}_2} &\leq \frac{1}{\tilde{\alpha}} \left\{ L_g (1 + \kappa_2^2)^{1/2} \|\mathbf{S}_2(\phi) - \mathbf{S}_2(\varphi)\|_{0,\Omega} \right. \\
&\quad \left. + L_\vartheta (1 + \kappa_1^2)^{1/2} \|\mathbf{S}_1(\phi) - \mathbf{S}_1(\varphi)\|_{0,\Omega} \|\tilde{\mathbf{S}}_1(\mathbf{S}_1(\varphi), \mathbf{S}_2(\varphi))\|_{\infty,\Omega} \right\}.
\end{aligned} \tag{3.30}$$

It is important to note here that, when needed, $\|\tilde{\mathbf{S}}_1(\mathbf{S}_1(\varphi), \mathbf{S}_2(\varphi))\|_{\infty,\Omega}$ can be bounded by (3.23), for each $\varphi \in \mathbf{H}^1(\Omega)$. Finally, applying estimates (3.24) and (3.30), we find that

$$\begin{aligned}
\|\mathbf{T}(\phi) - \mathbf{T}(\varphi)\|_{1,\Omega} &= \|\tilde{\mathbf{S}}_3(\mathbf{S}_1(\phi), \mathbf{S}_2(\phi)) - \tilde{\mathbf{S}}_3(\mathbf{S}_1(\varphi), \mathbf{S}_2(\varphi))\|_{1,\Omega} \\
&\leq \frac{1}{\tilde{\alpha}} C_S \left\{ L_g (1 + \kappa_2^2)^{1/2} + L_\vartheta (1 + \kappa_1^2)^{1/2} \|\tilde{\mathbf{S}}_1(\mathbf{S}_1(\varphi), \mathbf{S}_2(\varphi))\|_{\infty,\Omega} \right\} \|\phi - \varphi\|_{0,\Omega}.
\end{aligned}$$

which gives (3.25), completing the proof. \square

The next lemma establishes the continuity and compactness of \mathbf{T} .

Lemma 3.9 *Let W be as in Lemma 3.6. Then $\mathbf{T} : W \rightarrow W$ is continuous and $\overline{\mathbf{T}(W)}$ is compact.*

Proof. It follows straightforwardly from (3.25) and the continuity of $i_c : \mathbf{H}^1(\Omega) \rightarrow \mathbf{L}^2(\Omega)$ that

$$\|\mathbf{T}(\phi) - \mathbf{T}(\varphi)\|_{1,\Omega} \leq \frac{1}{\tilde{\alpha}} C_S \|i_c\| \left\{ L_g (1 + \kappa_2^2)^{1/2} + L_\vartheta (1 + \kappa_1^2)^{1/2} \|\tilde{\mathbf{S}}_1(\mathbf{S}_1(\varphi), \mathbf{S}_2(\varphi))\|_{\infty,\Omega} \right\} \|\phi - \varphi\|_{1,\Omega},$$

which proves continuity of \mathbf{T} . In turn, let $\{\phi_k\}_{k \in \mathbb{N}}$ be a sequence of W , which is clearly bounded. Then, there exists a subsequence $\{\phi_k^{(1)}\}_{k \in \mathbb{N}} \subseteq \{\phi_k\}_{k \in \mathbb{N}}$ and $\phi \in \mathbf{H}^1(\Omega)$ such that $\phi_k^{(1)} \xrightarrow{w} \phi \in \mathbf{H}^1(\Omega)$. In this way, thanks to the compactness of i_c , we deduce that $\phi_k^{(1)} \rightarrow \phi \in \mathbf{L}^2(\Omega)$, which, combined with (3.25), implies that $\mathbf{T}(\phi_k^{(1)}) \rightarrow \mathbf{T}(\phi) \in \mathbf{H}^1(\Omega)$, and proves the compactness of $\overline{\mathbf{T}(W)}$. \square

We are ready now to prove that (3.10) is well-posed. From Lemmas 3.6 and 3.9, the existence of solution is merely an application of Schauder's theorem. Furthermore, assuming that the data is small enough, we can prove uniqueness of solution. Details of the proof are similar to those available in [18, Thm. 2.9].

Theorem 3.10 *Let W be as in Lemma 3.6. Then, the augmented fully-mixed problem (3.9) has at least one solution $((\sigma, (\mathbf{u}, \rho)), (\mathbf{t}, \tilde{\sigma}, \phi)) \in \mathbf{H}_1 \times \mathbf{H}_2$ with $\phi \in W$, satisfying the bounds*

$$\begin{aligned}
\|(\mathbf{t}, \tilde{\sigma}, \phi)\|_{\mathbf{H}_2} &\leq \tilde{c}_S \left\{ \|\phi_D\|_{1/2,\Sigma} + g_2 |\Omega|^{1/2} \right\}, \\
\|(\sigma, (\mathbf{u}, \rho))\|_{\mathbf{H}_1} &\leq c_S \left\{ \|\mathbf{u}_D\|_{1/2,\Gamma} + f_2 |\Omega|^{1/2} \right\}.
\end{aligned}$$

Moreover, if the data satisfy

$$\frac{1}{\tilde{\alpha}} C_S \left\{ L_g (1 + \kappa_2^2)^{1/2} + L_\vartheta (1 + \kappa_1^2)^{1/2} C_\infty \left(\|\phi_D\|_{3/2+\gamma,\Sigma} + \|\mathbf{u}_D\|_{1/2,\Gamma} + f_2 |\Omega|^{1/2} \right) \right\} < 1,$$

then the solution ϕ is unique in W .

4 The Galerkin scheme

In this section we introduce and analyze a Galerkin scheme for (3.9). We adopt the discrete analogue of the fixed-point strategy introduced in Section 3.2 and apply the Brouwer fixed-point theorem to prove existence of discrete solution. Finally, we establish a priori error estimates. We start by considering generic finite dimensional subspaces

$$\mathbb{H}_h^\sigma \subseteq \mathbb{H}_\Sigma(\mathbf{div}; \Omega), \quad \mathbf{H}_h^u \subseteq \mathbf{L}^2(\Omega), \quad \mathbb{H}_h^\rho \subseteq \mathbb{L}_{\text{skew}}^2(\Omega), \quad (4.1)$$

$$\mathbf{H}_h^t \subseteq \mathbf{L}^2(\Omega), \quad \mathbf{H}_h^{\tilde{\sigma}} \subseteq \mathbf{H}_\Gamma(\mathbf{div}; \Omega), \quad \text{and} \quad \mathbf{H}_h^\phi \subseteq \mathbf{H}^1(\Omega), \quad (4.2)$$

which will be specified later on. Hereafter, h denotes the size of a regular triangulation \mathcal{T}_h of $\bar{\Omega}$ made up of triangles K of diameter h_K , i.e. $h := \max\{h_K : K \in \mathcal{T}_h\}$. A Galerkin scheme for (3.9) reads: find $(\boldsymbol{\sigma}_h, (\mathbf{u}_h, \boldsymbol{\rho}_h), \mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h) \in \mathbb{H}_h^\sigma \times (\mathbf{H}_h^u \times \mathbb{H}_h^\rho) \times \mathbf{H}_h^t \times \mathbf{H}_h^{\tilde{\sigma}} \times \mathbf{H}_h^\phi$ such that

$$\begin{aligned} a(\boldsymbol{\sigma}_h, \boldsymbol{\tau}_h) + b(\boldsymbol{\tau}_h, (\mathbf{u}_h, \boldsymbol{\rho}_h)) &= G(\boldsymbol{\tau}_h) & \forall \boldsymbol{\tau}_h \in \mathbb{H}_h^\sigma, \\ b(\boldsymbol{\sigma}_h, (\mathbf{v}_h, \boldsymbol{\eta}_h)) &= F_{\phi_h}(\mathbf{v}_h, \boldsymbol{\eta}_h) & \forall (\mathbf{v}_h, \boldsymbol{\eta}_h) \in \mathbf{H}_h^u \times \mathbb{H}_h^\rho, \\ A_{\boldsymbol{\sigma}_h}((\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h), (\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h)) &= G_{\mathbf{u}_h}(\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h) & \forall (\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h) \in \mathbf{H}_h^t \times \mathbf{H}_h^{\tilde{\sigma}} \times \mathbf{H}_h^\phi. \end{aligned} \quad (4.3)$$

In order to address the well-posedness of (4.3), we proceed analogously as in Section 3.2 and apply a fixed-point strategy. In fact, we define the operator $\mathbf{S}_h : \mathbf{H}_h^\phi \rightarrow \mathbb{H}_h^\sigma \times (\mathbf{H}_h^u \times \mathbb{H}_h^\rho)$ as

$$\mathbf{S}_h(\phi_h) := (\mathbf{S}_{1,h}(\phi_h), (\mathbf{S}_{2,h}(\phi_h), \mathbf{S}_{3,h}(\phi_h))) := (\boldsymbol{\sigma}_h, (\mathbf{u}_h, \boldsymbol{\rho}_h)) \quad \forall \phi_h \in \mathbf{H}_h^\phi,$$

where $(\boldsymbol{\sigma}_h, (\mathbf{u}_h, \boldsymbol{\rho}_h))$ is the unique solution of

$$\begin{aligned} a(\boldsymbol{\sigma}_h, \boldsymbol{\tau}_h) + b(\boldsymbol{\tau}_h, (\mathbf{u}_h, \boldsymbol{\rho}_h)) &= G(\boldsymbol{\tau}_h) & \forall \boldsymbol{\tau}_h \in \mathbb{H}_h^\sigma, \\ b(\boldsymbol{\sigma}_h, (\mathbf{v}_h, \boldsymbol{\eta}_h)) &= F_{\phi_h}(\mathbf{v}_h, \boldsymbol{\eta}_h) & \forall (\mathbf{v}_h, \boldsymbol{\eta}_h) \in \mathbf{H}_h^u \times \mathbb{H}_h^\rho, \end{aligned} \quad (4.4)$$

with F_{ϕ_h} being defined by (3.2) with $\phi = \phi_h$. In turn, we introduce $\tilde{\mathbf{S}}_h : \mathbb{H}_h^\sigma \times \mathbf{H}_h^u \rightarrow \mathbf{H}_h^t \times \mathbf{H}_h^{\tilde{\sigma}} \times \mathbf{H}_h^\phi$ as

$$\tilde{\mathbf{S}}_h(\boldsymbol{\sigma}_h, \mathbf{u}_h) := (\tilde{\mathbf{S}}_{1,h}(\boldsymbol{\sigma}_h, \mathbf{u}_h), \tilde{\mathbf{S}}_{2,h}(\boldsymbol{\sigma}_h, \mathbf{u}_h), \tilde{\mathbf{S}}_{3,h}(\boldsymbol{\sigma}_h, \mathbf{u}_h)) := (\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h) \quad \forall (\boldsymbol{\sigma}_h, \mathbf{u}_h) \in \mathbb{H}_h^\sigma \times \mathbf{H}_h^u,$$

where $(\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h)$ is the unique solution of

$$A_{\boldsymbol{\sigma}_h}((\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h), (\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h)) = G_{\mathbf{u}_h}(\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h) \quad \forall (\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h) \in \mathbf{H}_h^t \times \mathbf{H}_h^{\tilde{\sigma}} \times \mathbf{H}_h^\phi, \quad (4.5)$$

with $A_{\boldsymbol{\sigma}_h}$ and $G_{\mathbf{u}_h}$ being defined by (3.7) with $\boldsymbol{\sigma} = \boldsymbol{\sigma}_h$ and (3.8) with $\mathbf{u} = \mathbf{u}_h$, respectively. In this way, by introducing the operator $\mathbf{T}_h : \mathbf{H}_h^\phi \rightarrow \mathbf{H}_h^\phi$ as $\mathbf{T}_h(\phi_h) := \tilde{\mathbf{S}}_{3,h}(\mathbf{S}_{1,h}(\phi_h), \mathbf{S}_{2,h}(\phi_h)) \quad \forall \phi_h \in \mathbf{H}_h^\phi$, we realize that (4.3) can be rewritten as the fixed-point problem: find $\phi_h \in \mathbf{H}_h^\phi$ such that

$$\mathbf{T}_h(\phi_h) = \phi_h. \quad (4.6)$$

Analogously to the continuous case, we first study the well-posedness of \mathbf{S}_h and $\tilde{\mathbf{S}}_h$, and hence the well-definiteness of \mathbf{T}_h . To this end we proceed as in [18, Section 3.2] and incorporate further hypotheses on the discrete spaces \mathbb{H}_h^σ , \mathbf{H}_h^u and \mathbb{H}_h^ρ . Let V_h be the discrete kernel of b given by

$$V_h := \{\boldsymbol{\tau}_h \in \mathbb{H}_h^\sigma : b(\boldsymbol{\tau}_h, (\mathbf{v}_h, \boldsymbol{\eta}_h)) = 0 \quad \forall (\mathbf{v}_h, \boldsymbol{\eta}_h) \in \mathbf{H}_h^u \times \mathbb{H}_h^\rho\},$$

and assume the following discrete inf-sup conditions:

(H.0) There exists a constant $\alpha_1 > 0$, independent of h , such that

$$\sup_{\substack{\boldsymbol{\tau}_h \in V_h \\ \boldsymbol{\tau}_h \neq 0}} \frac{a(\boldsymbol{\sigma}_h, \boldsymbol{\tau}_h)}{\|\boldsymbol{\tau}_h\|_{\text{div};\Omega}} \geq \alpha_1 \|\boldsymbol{\sigma}_h\|_{\text{div};\Omega} \quad \forall \boldsymbol{\sigma}_h \in V_h. \quad (4.7)$$

(H.1) There exists a constant $\beta_1 > 0$, independent of h , such that

$$\sup_{\substack{\boldsymbol{\tau}_h \in \mathbb{H}_h^\sigma \\ \boldsymbol{\tau}_h \neq 0}} \frac{b(\boldsymbol{\tau}_h, (\mathbf{v}_h, \boldsymbol{\eta}_h))}{\|\boldsymbol{\tau}_h\|_{\text{div};\Omega}} \geq \beta_1 \|(\mathbf{v}_h, \boldsymbol{\eta}_h)\|_{\mathbf{L}^2(\Omega) \times \mathbb{L}_{\text{skew}}^2(\Omega)} \quad \forall (\mathbf{v}_h, \boldsymbol{\eta}_h) \in \mathbf{H}_h^{\mathbf{u}} \times \mathbb{H}_h^\rho. \quad (4.8)$$

Deriving well-posedness of the discrete problem (4.4) results as a straightforward application of the discrete Babuška-Brezzi theory. Firstly, the operators related to a and b , and the functionals G and F_{ϕ_h} are all bounded on subspaces of the corresponding continuous spaces. Next, the inf-sup conditions are given by (H.0) and (H.1). The unique solvability of (4.4) is abridged in the following lemma.

Lemma 4.1 *For each $\phi_h \in \mathbb{H}_h^\phi$, problem (4.4) has a unique solution $\mathbf{S}_h(\phi_h) := (\boldsymbol{\sigma}_h, (\mathbf{u}_h, \boldsymbol{\rho}_h)) \in \mathbb{H}_h^\sigma \times (\mathbf{H}_h^{\mathbf{u}} \times \mathbb{H}_h^\rho)$. Moreover, there exists $\tilde{C} > 0$, depending on μ, α_1 and β_1 (cf.(4.7), (4.8)), but independent of ϕ_h and h , such that*

$$\|\mathbf{S}_h(\phi_h)\|_{\mathbf{H}_1} = \|(\boldsymbol{\sigma}_h, (\mathbf{u}_h, \boldsymbol{\rho}_h))\|_{\mathbf{H}_1} \leq \tilde{C} \left\{ \|\mathbf{u}_D\|_{1/2, \Gamma} + f_2 |\Omega|^{1/2} \right\}.$$

Regard to problem $\tilde{\mathbf{S}}$ we state next the discrete analogue of Lemma 3.5.

Lemma 4.2 *Assume that $\kappa_1 \in \left(0, \frac{2\delta\vartheta_0}{\vartheta_2}\right)$ and $\kappa_3 \in \left(0, 2\tilde{\delta}\left(\vartheta_0 - \frac{\kappa_1\vartheta_2}{2\delta}\right)\right)$ with $\delta \in \left(0, \frac{2}{\vartheta_2}\right)$, $\tilde{\delta} \in (0, 2)$, and $\kappa_2, \kappa_4 > 0$. Then, for each $(\boldsymbol{\sigma}_h, \mathbf{u}_h) \in \mathbb{H}_h^\sigma \times \mathbf{H}_h^{\mathbf{u}}$, problem (4.5) has a unique solution $\tilde{\mathbf{S}}_h(\boldsymbol{\sigma}_h, \mathbf{u}_h) = (\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h) \in \mathbf{H}_h^{\mathbf{t}} \times \mathbf{H}_h^{\tilde{\boldsymbol{\sigma}}} \times \mathbb{H}_h^\phi$. Moreover, with the constant \tilde{c}_S provided by Lemma 3.5, there holds*

$$\|\tilde{\mathbf{S}}_h(\boldsymbol{\sigma}_h, \mathbf{u}_h)\|_{\mathbf{H}_2} = \|(\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h)\|_{\mathbf{H}_2} \leq \tilde{c}_S \left\{ \|\phi_D\|_{1/2, \Sigma} + g_2 |\Omega|^{1/2} \right\}. \quad (4.9)$$

Proof. We first observe that for each $(\boldsymbol{\sigma}_h, \mathbf{u}_h) \in \mathbb{H}_h^\sigma \times \mathbf{H}_h^{\mathbf{u}}$, the operator $A_{\boldsymbol{\sigma}_h}$ is bounded and elliptic on $\mathbf{H}_h^{\mathbf{t}} \times \mathbf{H}_h^{\tilde{\boldsymbol{\sigma}}} \times \mathbb{H}_h^\phi$ with the same constants $\|A\|$ and $\tilde{\alpha}$ from Lemma 3.5. In addition, $\tilde{G}_{\mathbf{u}_h}$ restricted to $\mathbf{H}_h^{\mathbf{t}} \times \mathbf{H}_h^{\tilde{\boldsymbol{\sigma}}} \times \mathbb{H}_h^\phi$ is bounded as in (3.19) with \mathbf{u}_h in place of \mathbf{u} . Therefore, the result is a direct application of the Lax-Milgram lemma. \square

We notice in advance that, instead of the regularity estimates employed in the continuous case (not applicable in the present discrete case), we simply utilize properties of the discrete subspaces chosen. In what follows, we verify the hypotheses of the Brouwer fixed-point theorem (see, e.g. [13, Thm. 9.9-2]) to prove that (4.6) has at least one fixed point.

Lemma 4.3 *Let $W_h := \left\{ \phi_h \in \mathbb{H}_h^\phi : \|\phi_h\|_{1, \Omega} \leq \tilde{c}_S \left\{ \|\phi_D\|_{1/2, \Sigma} + g_2 |\Omega|^{1/2} \right\} \right\}$. Then $\mathbf{T}_h(W_h) \subseteq W_h$.*

Proof. It is basically an application of the definition of \mathbf{T}_h and the estimate (4.9). \square

Lemma 4.4 *There exists $C > 0$ depending on μ, L_f, α_1 and β_1 (cf.(2.5), (4.7), (4.8)) such that*

$$\|\mathbf{S}_h(\phi_h) - \mathbf{S}_h(\varphi_h)\|_H \leq C \|\phi_h - \varphi_h\|_{0, \Omega} \quad \forall \phi_h, \varphi_h \in \mathbb{H}_h^\phi.$$

Proof. See [18, Lemma 3.4]. \square

Lemma 4.5 For each $(\boldsymbol{\sigma}_h, \mathbf{u}_h), (\boldsymbol{\zeta}_h, \mathbf{w}_h) \in \mathbb{H}_h^\sigma \times \mathbf{H}_h^u$, there holds

$$\begin{aligned} & \|\tilde{\mathbf{S}}_h(\boldsymbol{\sigma}_h, \mathbf{u}_h) - \tilde{\mathbf{S}}_h(\boldsymbol{\zeta}_h, \mathbf{w}_h)\|_{\mathbf{H}_2} \\ & \leq \frac{1}{\tilde{\alpha}} \left\{ L_g(1 + \kappa_2^2)^{1/2} \|\mathbf{u}_h - \mathbf{w}_h\|_{0,\Omega} + L_\vartheta(1 + \kappa_1^2)^{1/2} \|\tilde{\mathbf{S}}_{1,h}(\boldsymbol{\zeta}_h, \mathbf{w}_h)\|_{\infty,\Omega} \|\boldsymbol{\sigma}_h - \boldsymbol{\zeta}_h\|_{0,\Omega} \right\}. \end{aligned} \quad (4.10)$$

Proof. Proceeding as in [18, Lemma 3.5], given $(\boldsymbol{\sigma}_h, \mathbf{u}_h), (\boldsymbol{\zeta}_h, \mathbf{w}_h) \in \mathbb{H}_h^\sigma \times \mathbf{H}_h^u$, we let $(\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h) = \tilde{\mathbf{S}}_h(\boldsymbol{\sigma}_h, \mathbf{u}_h)$ and $(\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h) = \tilde{\mathbf{S}}_h(\boldsymbol{\zeta}_h, \mathbf{w}_h)$. Then, analogously to the proof of Lemma 3.8, we get

$$\begin{aligned} & \tilde{\alpha} \|(\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi) - (\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi)\|_{\mathbf{H}_2}^2 \\ & \leq \left\{ L_g(1 + \kappa_2^2)^{1/2} \|\mathbf{u}_h - \mathbf{w}_h\|_{0,\Omega} + L_\vartheta(1 + \kappa_1^2)^{1/2} \|\mathbf{r}_h\|_{\infty,\Omega} \|\boldsymbol{\sigma}_h - \boldsymbol{\zeta}_h\|_{0,\Omega} \right\} \|\phi_h - \varphi_h\|_{0,\Omega}. \end{aligned}$$

Since the elements of \mathbf{H}_h^t are piecewise polynomials (to be specified later on) it follows that $\|\mathbf{r}_h\|_{\infty,\Omega} < +\infty$, and hence the foregoing equation yields (4.10). Further details are omitted. \square

As a consequence of the above Lemmas, we can state the Lipschitz continuity of \mathbf{T} .

Lemma 4.6 Assume that C is as in Lemma 4.4. Then, for each $\phi_h, \varphi_h \in \mathbf{H}_h^\phi$, there holds

$$\begin{aligned} & \|\mathbf{T}_h(\phi_h) - \mathbf{T}_h(\varphi_h)\|_{1,\Omega} \\ & \leq \frac{C}{\tilde{\alpha}} \left\{ L_g(1 + \kappa_2^2)^{1/2} + L_\vartheta(1 + \kappa_1^2)^{1/2} \|\tilde{\mathbf{S}}_{1,h}(\mathbf{S}_{1,h}(\varphi), \mathbf{S}_{2,h}(\varphi))\|_{\infty,\Omega} \right\} \|\phi_h - \varphi_h\|_{0,\Omega}. \end{aligned}$$

Proof. It suffices to recall that $\mathbf{T}_h(\phi_h) = \tilde{\mathbf{S}}_{3,h}(\mathbf{S}_{1,h}(\phi_h), \mathbf{S}_{2,h}(\phi_h))$ for $\phi_h \in \mathbf{H}_h^\phi$ and apply Lemmas 4.3, 4.4 and 4.5. \square

At this point, we are able to state the main result of this section.

Theorem 4.7 Let $W_h := \left\{ \phi_h \in \mathbf{H}_h^\phi : \|\phi_h\|_{1,\Omega} \leq \tilde{c}_S \left\{ \|\phi_D\|_{1/2,\Sigma} + g_2|\Omega|^{1/2} \right\} \right\}$. Then (4.3) has at least one solution $(\boldsymbol{\sigma}_h, (\mathbf{u}_h, \boldsymbol{\rho}_h), \mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h) \in \mathbb{H}_h^\sigma \times (\mathbf{H}_h^u \times \mathbb{H}_h^\rho) \times \mathbf{H}_h^t \times \mathbf{H}_h^{\tilde{\boldsymbol{\sigma}}} \times \mathbf{H}_h^\phi$ with $\phi_h \in W_h$, and there holds

$$\|(\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h)\|_{\mathbf{H}_2} \leq \tilde{c}_S \left\{ \|\phi_D\|_{1/2,\Sigma} + g_2|\Omega|^{1/2} \right\}, \quad (4.11)$$

$$\|(\boldsymbol{\sigma}_h, (\mathbf{u}_h, \boldsymbol{\rho}_h))\|_{\mathbf{H}_1} \leq \tilde{C} \left\{ \|\mathbf{u}_D\|_{1/2,\Gamma} + f_2|\Omega|^{1/2} \right\}. \quad (4.12)$$

Proof. After using Lemmas 4.3 and 4.6, the result is a straightforward consequence of Brouwer's fixed-point theorem. In turn, bounds (4.11) and (4.12) follow from Lemmas 4.2 and 4.1, respectively. \square

In what follows, we derive an error estimate for (4.3). For this purpose, we consider in what follows $((\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho})), (\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi)) \in \mathbf{H}_1 \times \mathbf{H}_2$, with $\phi \in W$, and $(\boldsymbol{\sigma}_h, (\mathbf{u}_h, \boldsymbol{\rho}_h), \mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h) \in \mathbb{H}_h^\sigma \times (\mathbf{H}_h^u \times \mathbb{H}_h^\rho) \times \mathbf{H}_h^t \times \mathbf{H}_h^{\tilde{\boldsymbol{\sigma}}} \times \mathbf{H}_h^\phi$, with $\phi_h \in W_h$, be the solutions of (3.9) and (4.3), respectively. We seek an upper bound for

$$\|(\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho}), \mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\boldsymbol{\sigma}_h, (\mathbf{u}_h, \boldsymbol{\rho}_h), \mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h)\|,$$

for which, we suggest to estimate $\|(\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho})) - (\boldsymbol{\sigma}_h, (\mathbf{u}_h, \boldsymbol{\rho}_h))\|$ and $\|(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h)\|$, separately. With this goal in mind, we first rearrange (3.9) and (4.3) as follows

$$\begin{aligned} a(\boldsymbol{\sigma}, \boldsymbol{\tau}) + b(\boldsymbol{\tau}, (\mathbf{u}, \boldsymbol{\rho})) &= G(\boldsymbol{\tau}) & \forall \boldsymbol{\tau} \in \mathbb{H}_\Sigma(\mathbf{div}; \Omega), \\ b(\boldsymbol{\sigma}, (\mathbf{v}, \boldsymbol{\eta})) &= F_\phi(\mathbf{v}, \boldsymbol{\eta}) & \forall (\mathbf{v}, \boldsymbol{\eta}) \in \mathbf{L}^2(\Omega) \times \mathbb{L}_{\text{skew}}^2(\Omega), \\ a(\boldsymbol{\sigma}_h, \boldsymbol{\tau}_h) + b(\boldsymbol{\tau}_h, (\mathbf{u}_h, \boldsymbol{\rho}_h)) &= G(\boldsymbol{\tau}_h) & \forall \boldsymbol{\tau}_h \in \mathbb{H}_h^\sigma, \\ b(\boldsymbol{\sigma}_h, (\mathbf{v}_h, \boldsymbol{\eta}_h)) &= F_{\phi_h}(\mathbf{v}_h, \boldsymbol{\eta}_h) & \forall (\mathbf{v}_h, \boldsymbol{\eta}_h) \in \mathbf{H}_h^u \times \mathbb{H}_h^\rho \end{aligned} \quad (4.13)$$

and

$$\begin{aligned} A_{\boldsymbol{\sigma}}((\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi), (\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi)) &= G_{\mathbf{u}}(\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi) \quad \forall (\mathbf{s}, \tilde{\boldsymbol{\tau}}, \psi) \in \mathbf{H}_2, \\ A_{\boldsymbol{\sigma}_h}((\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h), (\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h)) &= G_{\mathbf{u}_h}(\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h) \quad \forall (\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h) \in \mathbf{H}_h^{\mathbf{t}} \times \mathbf{H}_h^{\tilde{\boldsymbol{\sigma}}} \times \mathbf{H}_h^{\phi}. \end{aligned} \quad (4.14)$$

Next, we recall from [31, Thm. 11.2 and 11.1] two instrumental results. First, a Strang inequality for saddle point problems where continuous and discrete formulations differ only in the functional. This will be applied to (4.13). Second, the standard Strang Lemma for elliptic problems, which fits (4.14).

Lemma 4.8 *Let H, Q be Hilbert spaces, let $\mathbf{a} : H \times H \rightarrow \mathbb{R}$ and $\mathbf{b} : H \times Q \rightarrow \mathbb{R}$ be bounded bilinear forms satisfying the Babuška-Brezzi theory, and let $F \in H'$ and $G \in Q'$. Let $\{H_h\}_{h>0}$ and $\{Q_h\}_{h>0}$ be sequences of finite-dimensional subspaces of H and Q , respectively. Suppose that \mathbf{a}, \mathbf{b} satisfy the hypotheses of the discrete Babuška-Brezzi theory uniformly on H_h and Q_h , that is, there exist positive constants $\hat{\alpha}$ and $\hat{\beta}$ independent of h , such that*

$$\sup_{\substack{\psi_h \in H_h \\ \psi_h \neq 0}} \frac{\mathbf{a}(\psi_h, \psi_h)}{\|\psi_h\|_H} \geq \hat{\alpha} \|\psi_h\|_H \quad \forall \psi_h \in V_h \quad \text{and} \quad \sup_{\substack{\psi_h \in H_h \\ \tau_h \neq 0}} \frac{\mathbf{b}(\psi_h, \mu_h)}{\|\psi_h\|_H} \geq \hat{\beta} \|\mu_h\|_Q \quad \forall \mu_h \in Q_h,$$

where V_h denotes the discrete kernel of \mathbf{b} . Moreover, for each $h > 0$, consider functionals $F_h \in H'_h$ and $G_h \in Q'_h$. Then, there exists a constant C_{ST} dependent only on $\|\mathbf{a}\|, \|\mathbf{b}\|, \hat{\alpha}$ and $\hat{\beta}$ such that if $(\varphi, \lambda) \in H \times Q$ and $(\varphi_h, \lambda_h) \in H_h \times Q_h$ satisfy the problems

$$\begin{aligned} \mathbf{a}(\varphi, \psi) + \mathbf{b}(\psi, \lambda) &= F(\psi) & \forall \psi \in H, \\ \mathbf{b}(\varphi, \mu) &= G(\mu) & \forall \mu \in Q, \end{aligned}$$

and

$$\begin{aligned} \mathbf{a}(\varphi_h, \psi_h) + \mathbf{b}(\psi_h, \lambda_h) &= F_h(\psi_h) & \forall \psi_h \in H_h, \\ \mathbf{b}(\varphi_h, \mu_h) &= G_h(\mu_h) & \forall \mu_h \in Q_h, \end{aligned}$$

respectively, then for each $h > 0$, there holds

$$\begin{aligned} \|\varphi - \varphi_h\|_H + \|\lambda - \lambda_h\|_Q &\leq C_{\text{ST}} \left\{ \inf_{\substack{\psi_h \in H_h \\ \psi_h \neq 0}} \|\varphi - \psi_h\|_H + \inf_{\substack{\mu_h \in Q_h \\ \mu_h \neq 0}} \|\lambda - \mu_h\|_Q \right. \\ &\quad \left. + \sup_{\substack{\phi_h \in H_h \\ \phi_h \neq 0}} \frac{|F(\phi_h) - F_h(\phi_h)|}{\|\phi_h\|_H} + \sup_{\substack{\eta_h \in Q_h \\ \eta_h \neq 0}} \frac{|G(\eta_h) - G_h(\eta_h)|}{\|\eta_h\|_H} \right\}. \end{aligned}$$

Lemma 4.9 *Let H be a Hilbert space, $F \in H'$ and $\mathbf{a} : H \times H \rightarrow \mathbb{R}$ be a bounded and elliptic bilinear form. In addition, let $\{H_h\}_{h>0}$ be a sequence of finite dimensional subspaces of H and for each $h > 0$ consider a bounded bilinear form $\mathbf{a}_h : H_h \times H_h \rightarrow \mathbb{R}$ and a functional $F_h \in H'_h$. Assume that the family $\{\mathbf{a}_h\}_{h>0}$ is uniformly elliptic, that is, there exists a constant $\alpha > 0$, independent of h , such that*

$$\mathbf{a}_h(v_h, v_h) \geq \alpha \|v_h\|_H^2 \quad \forall v_h \in H_h, \quad \forall h > 0.$$

In turn, let $u \in H$ and $u_h \in H_h$ such that

$$\mathbf{a}(u, v) = F(v) \quad \forall v \in H \quad \text{and} \quad \mathbf{a}_h(u_h, v_h) = F_h(v_h) \quad \forall v_h \in H_h.$$

Then, for each $h > 0$ there holds

$$\|u - u_h\|_H \leq \tilde{C}_{\text{ST}} \left\{ \sup_{\substack{w_h \in H_h \\ w_h \neq 0}} \frac{|F(w_h) - F_h(w_h)|}{\|w_h\|_H} + \inf_{\substack{v_h \in H_h \\ v_h \neq 0}} \left(\|u - v_h\|_V + \sup_{\substack{w_h \in H_h \\ w_h \neq 0}} \frac{|\mathbf{a}(v_h, w_h) - \mathbf{a}_h(v_h, w_h)|}{\|w_h\|_H} \right) \right\}.$$

where $\tilde{C}_{\text{ST}} := \alpha^{-1} \max\{1, \|\mathbf{a}\|\}$.

From now on, we denote as usual

$$\text{dist}((\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho})), \mathbb{H}_h^\boldsymbol{\sigma} \times (\mathbf{H}_h^{\mathbf{u}} \times \mathbb{H}_h^\boldsymbol{\rho})) := \inf_{(\boldsymbol{\tau}_h, (\mathbf{v}_h, \boldsymbol{\eta}_h)) \in \mathbb{H}_h^\boldsymbol{\sigma} \times (\mathbf{H}_h^{\mathbf{u}} \times \mathbb{H}_h^\boldsymbol{\rho})} \|(\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho})) - (\boldsymbol{\tau}_h, (\mathbf{v}_h, \boldsymbol{\eta}_h))\|_{\mathbf{H}_1},$$

and

$$\text{dist}((\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi), \mathbf{H}_h^{\mathbf{t}} \times \mathbf{H}_h^{\tilde{\boldsymbol{\sigma}}} \times \mathbf{H}_h^\phi) := \inf_{(\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h) \in \mathbf{H}_h^{\mathbf{t}} \times \mathbf{H}_h^{\tilde{\boldsymbol{\sigma}}} \times \mathbf{H}_h^\phi} \|(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h)\|_{\mathbf{H}_2}.$$

Next, a straightforward application of Lemma 4.8 yields the following result concerning a priori estimates for $\|(\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho})) - (\boldsymbol{\sigma}_h, (\mathbf{u}_h, \boldsymbol{\rho}_h))\|$. Details of the proof can be found in [18, Lemma 3.10].

Lemma 4.10 *There exists a constant $C_{\text{ST}} > 0$, depending on μ, α_1 and β_1 (cf. (4.7), (4.8)), such that*

$$\begin{aligned} & \|(\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho})) - (\boldsymbol{\sigma}_h, (\mathbf{u}_h, \boldsymbol{\rho}_h))\|_{\mathbf{H}_1} \\ & \leq C_{\text{ST}} \left\{ \text{dist}((\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho})), \mathbb{H}_h^\boldsymbol{\sigma} \times (\mathbf{H}_h^{\mathbf{u}} \times \mathbb{H}_h^\boldsymbol{\rho})) + L_f \|\phi - \phi_h\|_{0, \Omega} \right\}. \end{aligned} \quad (4.15)$$

In turn, we apply Lemma 4.9 to the pair (4.14) to obtain an estimate for $\|(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h)\|$.

Lemma 4.11 *Let $\tilde{C}_{\text{ST}} := \tilde{\alpha}^{-1} \max\{1, \|A\|\}$, where $\|A\|$ and $\tilde{\alpha}$ are the boundedness and ellipticity constants, respectively, of the bilinear form $A_\boldsymbol{\sigma}$ (cf. (3.16), (3.18)). Then, there holds*

$$\begin{aligned} \|(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h)\|_{\mathbf{H}_2} & \leq \tilde{C}_{\text{ST}} \left\{ (1 + 2\|A\|) \text{dist}((\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi), \mathbf{H}_h^{\mathbf{t}} \times \mathbf{H}_h^{\tilde{\boldsymbol{\sigma}}} \times \mathbf{H}_h^\phi) \right. \\ & \quad \left. + L_g(1 + \kappa_2^2)^{1/2} \|\mathbf{u} - \mathbf{u}_h\|_{0, \Omega} + L_\vartheta(1 + \kappa_1^2)^{1/2} \|\boldsymbol{\sigma} - \boldsymbol{\sigma}_h\|_{0, \Omega} \|\mathbf{t}\|_{\infty, \Omega} \right\}. \end{aligned} \quad (4.16)$$

Proof. A straightforward application of Lemma 4.11 to the context (4.14), gives

$$\begin{aligned} & \|(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h)\|_{\mathbf{H}_2} \\ & \leq \tilde{C}_{\text{ST}} \left\{ \sup_{\substack{(\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h) \in \mathbf{H}_h^{\mathbf{t}} \times \mathbf{H}_h^{\tilde{\boldsymbol{\sigma}}} \times \mathbf{H}_h^\phi \\ (\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h) \neq 0}} \frac{|G_{\mathbf{u}}(\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h) - G_{\mathbf{u}_h}(\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h)|}{\|(\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h)\|} \right. \\ & \quad + \inf_{\substack{(\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h) \in \mathbf{H}_h^{\mathbf{t}} \times \mathbf{H}_h^{\tilde{\boldsymbol{\sigma}}} \times \mathbf{H}_h^\phi \\ (\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h) \neq 0}} \left(\|(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h)\| \right. \\ & \quad \left. \left. + \sup_{\substack{(\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h) \in \mathbf{H}_h^{\mathbf{t}} \times \mathbf{H}_h^{\tilde{\boldsymbol{\sigma}}} \times \mathbf{H}_h^\phi \\ (\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h) \neq 0}} \frac{|A_\boldsymbol{\sigma}((\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h), (\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h)) - A_{\boldsymbol{\sigma}_h}((\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h), (\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h))|}{\|(\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h)\|} \right) \right\}. \end{aligned} \quad (4.17)$$

Then, proceeding analogously as in the proof of Lemma 3.8, we deduce that

$$\sup_{\substack{(\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h) \in \mathbf{H}_h^{\mathbf{t}} \times \mathbf{H}_h^{\tilde{\boldsymbol{\sigma}}} \times \mathbf{H}_h^{\phi} \\ (\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h) \neq 0}} \frac{|G_{\mathbf{u}}(\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h) - G_{\mathbf{u}_h}(\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h)|}{\|(\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h)\|} \leq L_g(1 + \kappa_2^2)^{1/2} \|\mathbf{u} - \mathbf{u}_h\|_{0,\Omega}. \quad (4.18)$$

In turn, in much the same way as [4, Lemma 5.2], we add and subtract suitable terms to write

$$\begin{aligned} & A_{\boldsymbol{\sigma}}((\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h), (\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h)) - A_{\boldsymbol{\sigma}_h}((\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h), (\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h)) \\ &= A_{\boldsymbol{\sigma}}((\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h) - (\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi), (\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h)) + (A_{\boldsymbol{\sigma}} - A_{\boldsymbol{\sigma}_h})((\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi), (\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h)) \\ & \quad + A_{\boldsymbol{\sigma}_h}((\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h), (\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h)), \end{aligned}$$

thus, the estimates for the first and third terms follow by applying the boundedness (3.16), whereas for the second one, we find that

$$\begin{aligned} (A_{\boldsymbol{\sigma}} - A_{\boldsymbol{\sigma}_h})((\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi), (\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h)) &= \int_{\Omega} (\vartheta(\boldsymbol{\sigma}) - \vartheta(\boldsymbol{\sigma}_h)) \mathbf{t} \cdot (\mathbf{r}_h - \kappa_1 \tilde{\boldsymbol{\zeta}}_h) \\ &\leq L_{\vartheta}(1 + \kappa_1^2)^{1/2} \|\boldsymbol{\sigma} - \boldsymbol{\sigma}_h\|_{0,\Omega} \|\mathbf{t}\|_{\infty,\Omega} \|(\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h)\|, \end{aligned}$$

whence, we deduce that

$$\begin{aligned} & \sup_{\substack{(\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h) \in \mathbf{H}_h^{\mathbf{t}} \times \mathbf{H}_h^{\tilde{\boldsymbol{\sigma}}} \times \mathbf{H}_h^{\phi} \\ (\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h) \neq 0}} \frac{|A_{\boldsymbol{\sigma}}((\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h), (\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h)) - A_{\boldsymbol{\sigma}_h}((\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h), (\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h))|}{\|(\mathbf{r}_h, \tilde{\boldsymbol{\zeta}}_h, \varphi_h)\|} \\ & \leq 2 \|A\| \|(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{s}_h, \tilde{\boldsymbol{\tau}}_h, \psi_h)\| + L_{\vartheta}(1 + \kappa_1^2)^{1/2} \|\boldsymbol{\sigma} - \boldsymbol{\sigma}_h\|_{0,\Omega} \|\mathbf{t}\|_{\infty,\Omega}. \end{aligned} \quad (4.19)$$

Finally, by replacing (4.18)-(4.19) into (4.17), we get (4.16), which ends the proof. \square

Now, to derive the C ea estimate for the total error we combine Lemmas 4.10 and 4.11. To this end, and for notational convenience, we introduce the following constants

$$C_1 := C_{\text{ST}} \tilde{C}_{\text{ST}} L_g (1 + \kappa_2^2)^{1/2}, \quad C_2 := C_{\text{ST}} \tilde{C}_{\text{ST}} C_{\infty} L_{\vartheta} (1 + \kappa_1^2)^{1/2}, \quad C_3 := \tilde{C}_{\text{ST}} (1 + 2 \|A\|).$$

Next we replace the bounds for $\|\mathbf{u} - \mathbf{u}_h\|_{0,\Omega}$ and $\|\boldsymbol{\sigma} - \boldsymbol{\sigma}_h\|_{0,\Omega}$ into (4.16), and apply from (3.23) that

$$\|\mathbf{t}\|_{\infty,\Omega} \leq C_{\infty} \left\{ \|\phi_{\text{D}}\|_{3/2+\gamma,\Sigma} + \|\mathbf{u}_{\text{D}}\|_{1/2,\Gamma} + f_2 |\Omega|^{1/2} \right\}.$$

We then perform algebraic manipulations to find that

$$\begin{aligned} & \|(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h)\|_{\mathbf{H}_2} \\ & \leq \left\{ C_1 + C_2 \left(\|\phi_{\text{D}}\|_{3/2+\gamma,\Sigma} + \|\mathbf{u}_{\text{D}}\|_{1/2,\Gamma} + f_2 |\Omega|^{1/2} \right) \right\} \text{dist}((\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho}), \mathbf{H}_h^{\boldsymbol{\sigma}} \times (\mathbf{H}_h^{\mathbf{u}} \times \mathbf{H}_h^{\boldsymbol{\rho}})) \\ & \quad + L_f \left\{ C_1 + C_2 \left(\|\phi_{\text{D}}\|_{3/2+\gamma,\Sigma} + \|\mathbf{u}_{\text{D}}\|_{1/2,\Gamma} + f_2 |\Omega|^{1/2} \right) \right\} \|(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h)\| \\ & \quad + C_3 \text{dist}((\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi), \mathbf{H}_h^{\mathbf{t}} \times \mathbf{H}_h^{\tilde{\boldsymbol{\sigma}}} \times \mathbf{H}_h^{\phi}) \end{aligned} \quad (4.20)$$

Consequently, we can establish the following result which provides the complete C ea estimate.

Theorem 4.12 *Suppose that the data satisfy*

$$L_f \left\{ C_1 + C_2 \left(\|\phi_{\text{D}}\|_{3/2+\gamma,\Sigma} + \|\mathbf{u}_{\text{D}}\|_{1/2,\Gamma} + f_2 |\Omega|^{1/2} \right) \right\} < \frac{1}{2}.$$

Then, there exist positive constants C_4 and C_5 independent of h , such that

$$\begin{aligned} & \|(\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho})) - (\boldsymbol{\sigma}_h, (\mathbf{u}_h, \boldsymbol{\rho}_h))\|_{\mathbf{H}_1} + \|(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h)\|_{\mathbf{H}_2} \\ & \leq C_4 \text{dist}((\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho})), \mathbb{H}_h^{\boldsymbol{\sigma}} \times (\mathbf{H}_h^{\mathbf{u}} \times \mathbb{H}_h^{\boldsymbol{\rho}})) + C_5 \text{dist}((\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi), \mathbf{H}_h^{\mathbf{t}} \times \mathbf{H}_h^{\tilde{\boldsymbol{\sigma}}} \times \mathbf{H}_h^{\phi}). \end{aligned} \quad (4.21)$$

Proof. It follows straightforwardly from (4.15) and (4.20). \square

We now specify finite element subspaces satisfying (4.1)-(4.2) and the discrete inf-sup conditions (H.0)-(H.1). Given an integer $k \geq 0$, for each $K \in \mathcal{T}_h$ we let $\mathbf{P}_k(K)$ be the space of polynomial functions on K of degree $\leq k$ and define the local Raviart-Thomas space of order k as

$$\mathbf{RT}_k(K) := \mathbf{P}_k(K) \oplus \mathbf{P}_k(K) \mathbf{x}$$

where $\mathbf{P}_k(K) = [\mathbf{P}_k(K)]^2$, and \mathbf{x} is the generic vector in \mathbb{R}^2 . Let b_K be the element bubble function defined as the unique polynomial in $\mathbf{P}_{k+1}(K)$ vanishing on ∂K with $\int_K b_K = 1$. Then, for each $K \in \mathcal{T}_h$ we consider the bubble space of order k , defined by

$$\mathbf{B}_k(K) := \mathbf{P}_k(K) \left(\frac{\partial b_K}{\partial x_2}, -\frac{\partial b_K}{\partial x_1} \right).$$

One option to approximate stress, displacement and rotation is the classical PEERS elements [6]:

$$\begin{aligned} \mathbb{H}_h^\sigma &:= \{ \boldsymbol{\tau}_h \in \mathbb{H}_\Sigma(\mathbf{div}; \Omega) : \boldsymbol{\tau}_h|_K \in \mathbf{RT}_k(K) \oplus \mathbf{B}_k(K) \quad \forall K \in \mathcal{T}_h \}, \\ \mathbf{H}_h^u &:= \{ \mathbf{v}_h \in \mathbf{L}^2(\Omega) : \mathbf{v}_h|_K \in \mathbf{P}_k(K) \quad \forall K \in \mathcal{T}_h \}, \\ \mathbb{H}_h^\rho &:= \{ \boldsymbol{\eta}_h \in \mathbb{L}_{\text{skew}}^2(\Omega) : \boldsymbol{\eta}_h \in \mathbf{C}(\Omega) \quad \text{and} \quad \boldsymbol{\eta}_h|_K \in \mathbb{P}_{k+1}(K) \quad \forall K \in \mathcal{T}_h \}. \end{aligned} \quad (4.22)$$

We could also employ the Arnold-Falk-Winther (AFW, [8]) elements for the elasticity unknowns:

$$\begin{aligned} \mathbb{H}_h^\sigma &:= \{ \boldsymbol{\tau}_h \in \mathbb{H}_\Sigma(\mathbf{div}; \Omega) : \boldsymbol{\tau}_h|_K \in \mathbf{BDM}_{k+1}(K) \quad \forall K \in \mathcal{T}_h \}, \\ \mathbf{H}_h^u &:= \{ \mathbf{v}_h \in \mathbf{L}^2(\Omega) : \mathbf{v}_h|_K \in \mathbf{P}_k(K) \quad \forall K \in \mathcal{T}_h \}, \\ \mathbb{H}_h^\rho &:= \{ \boldsymbol{\eta}_h \in \mathbb{L}_{\text{skew}}^2(\Omega) : \boldsymbol{\eta}_h|_K \in \mathbb{P}_k(K) \quad \forall K \in \mathcal{T}_h \}, \end{aligned} \quad (4.23)$$

and recall that both PEERS and AFW satisfy (H.0) and (H.1) (cf. [6, Lemma 4.4], [7, Thm. 11.9]).

In turn, we define the approximating spaces for the concentration gradient, diffusive flux and solute concentration as piecewise polynomials of degree $\leq k$, Raviart-Thomas elements of order k , and Lagrange finite elements up to degree $k+1$, respectively:

$$\begin{aligned} \mathbf{H}_h^t &:= \{ \mathbf{t}_h \in \mathbf{L}^2(\Omega) : \mathbf{t}_h|_K \in \mathbf{P}_k(K) \quad \forall K \in \mathcal{T}_h \}, \\ \mathbf{H}_h^{\tilde{\sigma}} &:= \{ \tilde{\boldsymbol{\tau}}_h \in \mathbf{H}_\Gamma(\mathbf{div}; \Omega) : \tilde{\boldsymbol{\tau}}_h|_K \in \mathbf{RT}_k(K) \quad \forall K \in \mathcal{T}_h \}, \\ \mathbf{H}_h^\phi &:= \{ \psi_h \in \mathbf{C}(\Omega) \quad \psi_h|_K \in \mathbf{P}_{k+1}(K) \quad \forall K \in \mathcal{T}_h \}. \end{aligned} \quad (4.24)$$

Approximation properties of the spaces in (4.22), (4.23), (4.24) can be found in e.g. [10, 16]. They can be combined with the C ea estimate (4.21) and the assumption of adequately small data, to produce the theoretical rates of convergence of (4.3), summarized in what follows.

Theorem 4.13 *In addition to the hypotheses of Theorems 3.10, 4.7 and 4.12, assume that there exists $s > 0$ such that $\boldsymbol{\sigma} \in \mathbb{H}^s(\Omega)$, $\mathbf{div} \boldsymbol{\sigma} \in \mathbf{H}^s(\Omega)$, $\mathbf{u} \in \mathbf{H}^s(\Omega)$, $\boldsymbol{\rho} \in \mathbb{H}^s(\Omega)$, $\mathbf{t} \in \mathbf{H}^s(\Omega)$, $\tilde{\boldsymbol{\sigma}} \in \mathbf{H}^s(\Omega)$, $\mathbf{div} \tilde{\boldsymbol{\sigma}} \in \mathbf{H}^s(\Omega)$ and $\phi \in \mathbf{H}^{1+s}(\Omega)$. Then, there exists $\tilde{C} > 0$, independent of h , such that, with the finite element subspaces defined by either (4.22) or (4.23) and (4.24), there holds*

$$\begin{aligned} & \|(\boldsymbol{\sigma}, (\mathbf{u}, \boldsymbol{\rho})) - (\boldsymbol{\sigma}_h, (\mathbf{u}_h, \boldsymbol{\rho}_h))\|_{\mathbf{H}_1} + \|(\mathbf{t}, \tilde{\boldsymbol{\sigma}}, \phi) - (\mathbf{t}_h, \tilde{\boldsymbol{\sigma}}_h, \phi_h)\|_{\mathbf{H}_2} \leq \tilde{C} h^{\min\{s, k+1\}} \left\{ \|\boldsymbol{\sigma}\|_{s, \Omega} \right. \\ & \left. + \|\mathbf{div} \boldsymbol{\sigma}\|_{s, \Omega} + \|\mathbf{u}\|_{s, \Omega} + \|\boldsymbol{\rho}\|_{s, \Omega} + \|\mathbf{t}\|_{s, \Omega} + \|\tilde{\boldsymbol{\sigma}}\|_{s, \Omega} + \|\mathbf{div} \tilde{\boldsymbol{\sigma}}\|_{s, \Omega} + \|\phi\|_{1+s, \Omega} \right\}. \end{aligned}$$

Augmented $\mathbf{BDM}_1 - \mathbf{P}_0 - \mathbb{P}_0 - \mathbf{RT}_0 - \mathbf{P}_0 - \mathbf{P}_1$ scheme							
N	h	$e(\boldsymbol{\sigma})$	$r(\boldsymbol{\sigma})$	$e(\mathbf{u})$	$r(\mathbf{u})$	$e(\boldsymbol{\rho})$	$r(\boldsymbol{\rho})$
129	0.7071	1.36202	-	2.115e-02	-	5.612e-02	-
465	0.3536	0.71603	0.9276	1.045e-02	1.0180	2.647e-02	1.0840
1761	0.1768	0.36244	0.9823	5.083e-03	1.0390	1.258e-02	1.0730
6849	0.0883	0.18184	0.9950	2.512e-03	1.0170	6.143e-03	1.0340
27009	0.0441	0.09102	0.9984	1.252e-03	1.0050	3.048e-03	1.0110
107265	0.0221	0.04552	0.9994	6.252e-04	1.0010	1.520e-03	1.0030
	$e(\mathbf{t})$	$r(\mathbf{t})$	$e(\tilde{\boldsymbol{\sigma}})$	$r(\tilde{\boldsymbol{\sigma}})$	$e(\phi)$	$r(\phi)$	iter
	3.947e-02	-	1.352e-01	-	4.391e-02	-	5
	2.293e-02	0.7834	7.375e-02	0.8744	2.458e-02	0.8372	5
	1.197e-02	0.9383	3.765e-02	0.9700	1.318e-02	0.8992	5
	6.053e-03	0.9833	1.891e-02	0.9933	6.802e-03	0.9541	5
	3.035e-03	0.9957	9.466e-03	0.9985	3.442e-03	0.9828	5
	1.519e-03	0.9989	4.734e-03	0.9996	1.728e-03	0.9942	5

Augmented $\mathbf{BDM}_2 - \mathbf{P}_1 - \mathbb{P}_1 - \mathbf{RT}_1 - \mathbf{P}_1 - \mathbf{P}_2$ scheme							
N	h	$e(\boldsymbol{\sigma})$	$r(\boldsymbol{\sigma})$	$e(\mathbf{u})$	$r(\mathbf{u})$	$e(\boldsymbol{\rho})$	$r(\boldsymbol{\rho})$
337	0.7071	0.40398	-	5.723e-03	-	1.350e-02	-
1265	0.3536	0.10652	1.9230	1.471e-03	1.9600	3.423e-03	1.9800
4897	0.1768	0.02701	1.9800	3.718e-04	1.9850	8.692e-04	1.9770
19265	0.0883	0.00677	1.9950	9.323e-05	1.9960	2.189e-04	1.9900
76417	0.0441	0.00169	1.9990	2.333e-05	1.9990	5.486e-05	1.9960
304385	0.0221	0.00042	2.0000	5.833e-06	2.0000	1.373e-05	1.9990
	$e(\mathbf{t})$	$r(\mathbf{t})$	$e(\tilde{\boldsymbol{\sigma}})$	$r(\tilde{\boldsymbol{\sigma}})$	$e(\phi)$	$r(\phi)$	iter
	1.360e-02	-	4.501e-02	-	1.487e-02	-	5
	4.028e-03	1.7506	1.285e-02	1.8080	4.311e-03	1.7860	5
	1.059e-03	1.9270	3.323e-03	1.9520	1.153e-03	1.9020	5
	2.692e-04	1.9760	8.381e-04	1.9870	2.986e-04	1.9500	5
	6.773e-05	1.9910	2.100e-04	1.9970	7.598e-05	1.9740	5
	1.697e-05	1.9960	5.254e-05	1.9990	1.917e-05	1.9870	5

Table 1: Example 1: Convergence history and Picard iteration count for the augmented $\mathbf{BDM}_{k+1} - \mathbf{P}_k - \mathbb{P}_k - \mathbf{RT}_k - \mathbf{P}_k - \mathbf{P}_{k+1}$ approximations with $k = 0, 1$. Here N stands for the number of degrees of freedom associated to the each triangulation \mathcal{T}_h .

5 Numerical results

In this section we present some examples illustrating the performance of our augmented fully-mixed scheme (4.3), and confirming the rates of convergence provided by Theorem 4.13. These numerical results also include examples in which some of the data do not necessarily satisfy all the hypotheses required, thus confirming the potentiality of the method proposed, and also evidencing that only technical limitations are preventing us from extending our theoretical analysis to more general cases. Our implementation is based on the FEniCS library [2]. In turn, a Picard algorithm with tolerance of $1e-6$ on the ℓ^∞ -norm of the residual has been employed for the fixed-point problem (4.6). For the diffusion sub-problem in Examples 2 and 3 we have utilized the variational formulation (3.4) applying a fixed-point on $\boldsymbol{\sigma}$ and \mathbf{t} ; and $\boldsymbol{\sigma}$ and ϕ , respectively. There we have also considered Raviart-Thomas elements of order k for the flux and the concentration gradient, and piecewise polynomials of degree $\leq k$ for the concentration (see the method developed in [19]).

Example 1. In our first numerical test we take the unit square as computational domain $\Omega = (0, 1)^2$, the boundary $\partial\Omega = \bar{\Gamma} \cup \bar{\Sigma}$, with $\bar{\Sigma} := \{0\} \times (0, 1) \cup (0, 1) \times \{1\}$ and $\bar{\Gamma} := \partial\Omega \setminus \bar{\Sigma}$, and choose the

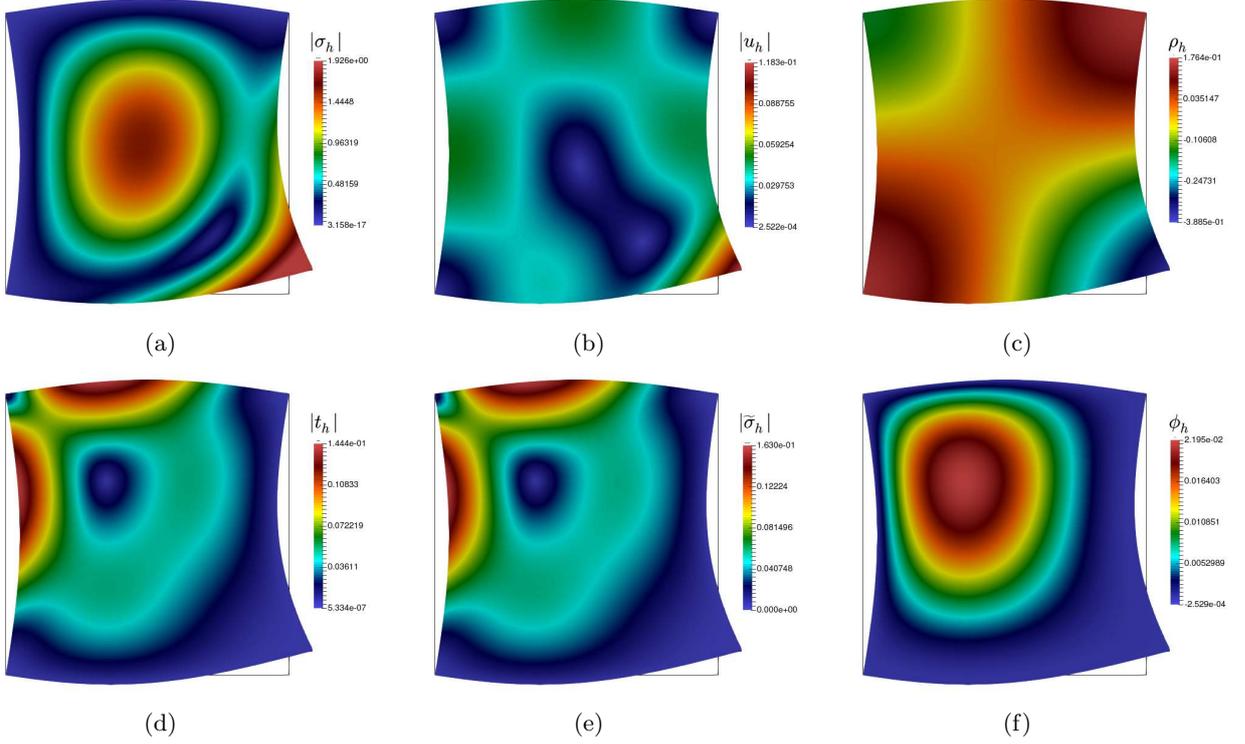


Figure 1: Example 1: Lowest-order approximation of stress magnitude $|\boldsymbol{\sigma}_h|$ (a), displacement magnitude $|\mathbf{u}_h|$ (b), relevant component of the rotation $\boldsymbol{\rho}_h$ (c), gradient of concentration $|\mathbf{t}_h|$ (d), diffusive flux $|\tilde{\boldsymbol{\sigma}}_h|$ (e), and solute concentration ϕ_h (f). All fields are plotted on the deformed domain.

following manufactured exact solutions and coupling terms to (3.9):

$$\begin{aligned}
 \mathbf{u} &= \begin{pmatrix} d_1 \cos(\pi x_1) \sin(\pi x_2) + \frac{x_1^2(1-x_2)^2}{2\lambda} \\ -d_1 \sin(\pi x_1) \cos(\pi x_2) + \frac{x_1^3(1-x_2)^3}{2\lambda} \end{pmatrix}, \quad \boldsymbol{\sigma} = \lambda \operatorname{tr} \boldsymbol{\varepsilon}(\mathbf{u}) \mathbb{I} + 2\mu \boldsymbol{\varepsilon}(\mathbf{u}), \quad \boldsymbol{\rho} = \nabla u - \boldsymbol{\varepsilon}(\mathbf{u}), \\
 \phi &= (1-x_1)^2 x_1 (1-x_2) x_2^2, \quad \mathbf{t} = \nabla \phi, \quad \tilde{\boldsymbol{\sigma}} = \vartheta(\boldsymbol{\sigma}) \mathbf{t}, \\
 \vartheta(\boldsymbol{\sigma}) &= (D_0 + D_1(1-|\boldsymbol{\sigma}|^2)^{-0.5}) \mathbb{I}, \quad \mathbf{f}(\phi) = d_2 \begin{pmatrix} \cos(\phi) \\ -\sin(\phi) \end{pmatrix}, \quad g(\mathbf{u}) = 2 + \frac{1}{1+|\mathbf{u}|^2}.
 \end{aligned} \tag{5.1}$$

We note that the tensorial diffusivity, body load and diffusive source terms satisfy (2.5)-(2.7) and (2.8). Moreover, the elasticity and diffusion equations are considered non-homogeneous and the extra source terms are chosen according to (5.1). This treatment does not compromise the continuous and discrete analysis, as the smoothness of the exact solution provides right-hand sides with terms in $L^2(\Omega)$, thus only requiring a slight modification of the functionals in the variational formulation. The Lamé constants $\lambda = E\nu/(1+\nu)^{-1}(1-2\nu)^{-1}$ and $\mu = E/(2+2\nu)$ are computed using the values $E = 10$ and $\nu = 0.3$ [39]. The remaining model parameters are given by: $d_1 = 0.05$, $d_2 = 0.1$, $D_0 = 1.0$, $D_1 = 0.1$, and according to (3.20), the stabilization parameters are taken as $\kappa_1 = \vartheta_0/\vartheta_2^2$, $\kappa_2 = \vartheta_0/2\vartheta_2^2$, $\kappa_3 = \vartheta_0/2$ and $\kappa_4 = \vartheta_0/4$. The convergence of the approximate solutions is assessed by computing errors in the respective norms and experimental rates, that we define as usual

$$\begin{aligned}
 e(\boldsymbol{\sigma}) &= \|\boldsymbol{\sigma} - \boldsymbol{\sigma}_h\|_{\operatorname{div};\Omega}, \quad e(\mathbf{u}) = \|\mathbf{u} - \mathbf{u}_h\|_{0,\Omega}, \quad e(\boldsymbol{\rho}) = \|\boldsymbol{\rho} - \boldsymbol{\rho}_h\|_{0,\Omega}, \quad e(\mathbf{t}) = \|\mathbf{t} - \mathbf{t}_h\|_{0,\Omega}, \\
 e(\tilde{\boldsymbol{\sigma}}) &= \|\tilde{\boldsymbol{\sigma}} - \tilde{\boldsymbol{\sigma}}_h\|_{\operatorname{div};\Omega}, \quad e(\phi) = \|\phi - \phi_h\|_{1,\Omega}, \quad r(\cdot) = \log(e(\cdot)/\hat{e}(\cdot))[\log(h/\hat{h})]^{-1},
 \end{aligned}$$

where e, \hat{e} denote errors computed on two consecutive meshes of sizes h, \hat{h} , respectively. We choose the finite element spaces (4.23) and (4.24), that is $\mathbf{BDM}_{k+1} - \mathbf{P}_k - \mathbb{P}_k - \mathbf{RT}_k - \mathbf{P}_k - \mathbf{P}_{k+1}$ approximations

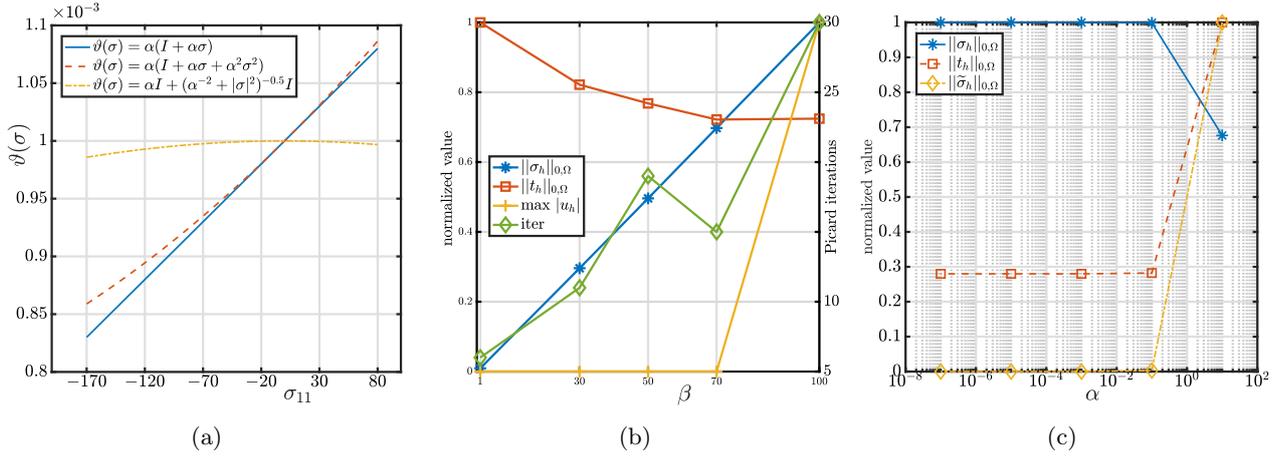


Figure 2: Example 2. Approximation of different functions $\vartheta(\sigma)$ varying the σ_{11} component (a), normalized L^2 -norm for σ_h and t_h , ℓ^∞ -norm for u_h and number of Picard iterations needed for different values of β with $E=100$ (b), and normalized L^2 -norm for σ_h , t_h and $\tilde{\sigma}_h$ for five different values of α (c).

with $k = 0$ and $k = 1$. Errors and decay rates are summarized in Table 1, where we observe that optimal convergence $O(h^{k+1})$ is attained for all fields in their relevant norms. These findings are in agreement with the bounds given by Theorem 4.13. In all cases, five Picard steps were required to reach the desired tolerance. Sample solutions are displayed in Figure 1.

Example 2. Next we concentrate on the simulation of microscopic lithiation of an anode. Details on model derivation and physical considerations can be found, for instance, in [11, 26, 35]. The domain consists of a truncated sphere of radius $10 \mu\text{m}$, representing the silicon core of a secondary particle (see Figure 3(a)), which we discretize using an unstructured mesh of 104913 tetrahedral elements. We assume that the face of the truncated sphere which is closest to the plane $x_1 = 0$ (denoted Γ) is in contact with a region of electrolyte, that is, the zone between the sphere and the surrounding cube. On Γ we set zero-flux of lithium and also consider that the anode has an external layer that does not permit displacement of the body, so there we set $\mathbf{u} = \mathbf{0}$. On the remainder of the boundary $\Sigma = \partial\Omega \setminus \Gamma$, we prescribe a maximum lithium concentration $\phi = \phi_{\max}$ with $\phi_{\max} = 26390$, as well as $\sigma\nu = \beta\phi\mathbb{I}\nu$, where β is a parameter to be specified later on. We assume that the source term is zero, and the diffusivity is specified as $\vartheta(\sigma) = D_0\mathbb{I} + D_1\sigma$ with $D_0 = 1.2\text{e-}21 \text{ m}^2\text{s}^{-1}$, $D_1 = 3.9\text{e-}14 \text{ m}^2\text{s}^{-1}$, and the elastic material properties of silicon are $E = 60\text{GPa}$ and $\nu = 0.25$. Following the referenced models, here the total stress contains a contribution due to lithium concentration. More specifically, we consider $\sigma^{\text{tot}} = \sigma - \beta\phi\mathbb{I}$, with $\beta = \hat{\Omega}(3\lambda + 2\mu)/3$, where $\hat{\Omega} = 4.926\text{e-}6 \text{ m}^3 \text{ mol}^{-1}$ is the partial molar volume. The balance of momentum is then $-\text{div } \sigma = -\beta\nabla\phi$, or equivalently $-\text{div } \sigma^{\text{tot}} = \mathbf{0}$ and the zero traction boundary condition can be recast as $\sigma^{\text{tot}}\nu = \mathbf{0}$ on Σ .

In order to have a model with fewer chemical and physical parameters, and also to accommodate a model with adimensional units, we proceed to rescale the strong form of the governing equations and testing different deformation regimes to match the expected values found in the literature. We introduce the following parameters: the intrinsic size of the domain $L = 1.6\text{e-}5 \text{ m}^2$, $\nabla^* = \nabla/L$, $\text{div}^* = \text{div}/L$, $\phi^* = \phi/\phi_{\max}$, $\mathbf{u}^* = \mathbf{u}/L$ and $\sigma^* = L^2\sigma$. Thus, taking $D_0 = 1.0\text{e-}2D_1L^2$, we reduce the parameters $D_0, D_1, \beta, \hat{\Omega}$ given above to only $\beta^* = \beta\phi_{\max}/L^2$ and $\alpha = 1.0\text{e-}2D_1L^2\phi_{\max}$. Making abuse of notation, we rename β^* by β , \mathbf{u}^* by \mathbf{u} , and so on. The proper scaling of the parameters implies that the baseline case corresponds to $\beta = 5.0\text{e}1$ and $\alpha = 1.0\text{e-}3$.

Figure 3(i) illustrates the sharp transition between high and low concentrations as lithium diffuses

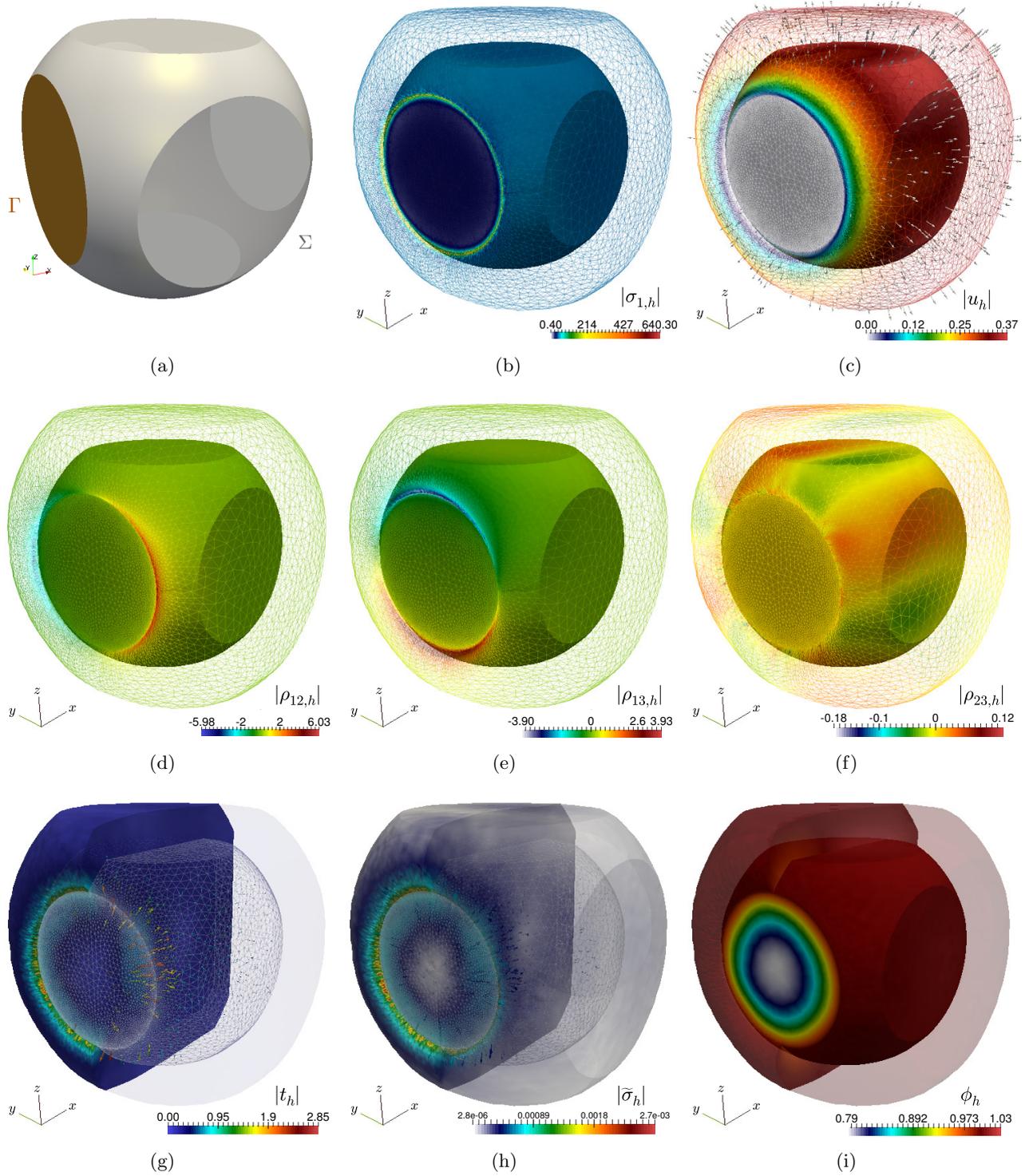


Figure 3: Example 2. Schematic representation of domain boundaries on a secondary particle silicone anode (a), lowest-order approximation of stress magnitude $|\sigma_h|$ (b), displacement magnitude $|u_h|$ (c), rotation components (d,e,f), concentration gradient $|t_h|$ (g), diffusive flux $|\tilde{\sigma}_h|$ (h), and solute concentration ϕ_h (i).

from Σ into the secondary particle. In addition, Figure 3(c) shows more pronounced displacements near Σ (which is precisely the region where the silicon is fully lithiated), and the particle swelling is indeed

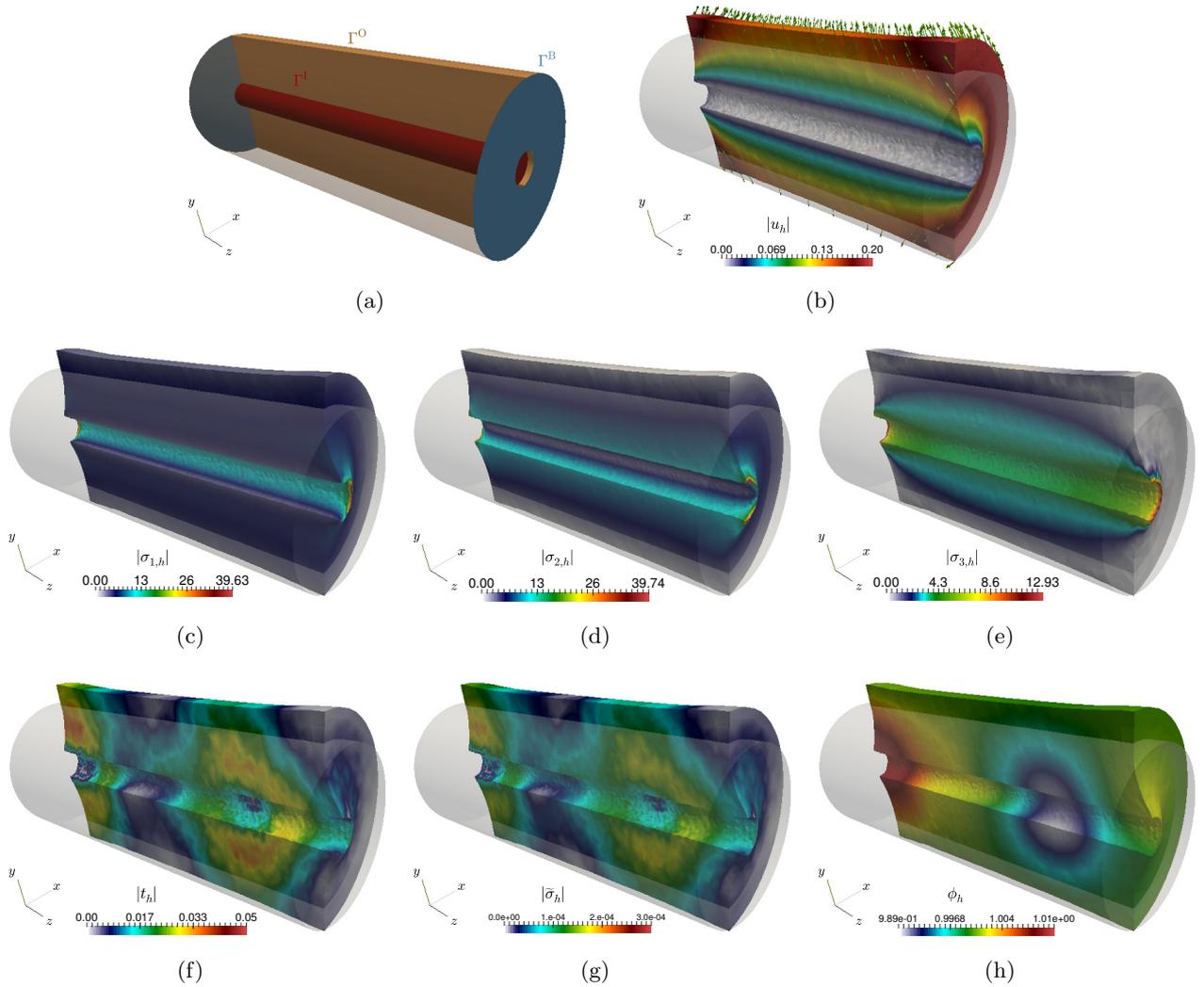


Figure 4: Example 3: Geometry for a perforated cylindrical particle (a), approximate displacement magnitude (b), magnitude of the rows of the approximate Cauchy stress (c,d,e), concentration gradient (f), diffusive flux (g), and concentration (h) shown on a clipped geometry.

influenced by the lithium gradient distribution. The stress-assisted diffusion mechanism together with the dilation-dependent source term, also contribute to maintain maximum lithium concentration near Σ . This two-way coupling effect implies in turn that the lithium concentration is less important in regions where the secondary particle is clamped.

In Figure 2 we show three different constitutive relations defining ϑ as a function of the first component of the Cauchy stress tensor. The first and third specifications correspond to the functions used in this test and in the accuracy example, respectively, whereas the second relationship has been used in [12] in the context of biological materials. Depending on the values attained by the stress, one could then easily derive the values of the augmentation constants. On the other hand, in Figures 2(b) and 2(c) we report a study on the influence of different values of the coupling constants β and α into the norms of selected solution fields for the elasticity and diffusion problems. We remark that the ℓ^∞ -norm of \mathbf{u}_h is practically invariant to moderate values of β , but it increases abruptly when this parameter approaches 70. Furthermore, the \mathbf{L}^2 -norm of the stress increases linearly with β . As this constant drives the intensity of the deformation as well as the coupling strength, we also observe an increase in the Picard iteration count (where we stress that all fields are normalized). We also observe

an increase of the \mathbf{L}^2 -norm of the concentration gradient with respect to α , while for smaller values of α the method produces higher values of the \mathbf{L}^2 -norm of $\tilde{\sigma}$.

Example 3. In our last example we test a similar model defined on a perforated cylindrical particle (see a sketch in Figure 4(a)). The outer and inner radii of the bases are $5\ \mu\text{m}$ and $1\ \mu\text{m}$, respectively, and the height of the cylinder is $25\ \mu\text{m}$. We discretize the domain using an unstructured mesh of 101907 tetrahedral elements. We consider that the particle is clamped on the inner wall Γ^I , while zero lithium fluxes is prescribed on $\Gamma^B \cup \Gamma^I$. Also, we fix a maximum lithium concentration on Γ^O , whereas zero traction will be imposed on $\Gamma^B \cup \Gamma^O$. We let $E = 10\text{GPa}$, $\nu = 0.3$ and $\widehat{\Omega} = 3.497\text{e-}6\ \text{m}^3\ \text{mol}^{-1}$. The diffusive source is zero and the diffusivity tensor and body load source are given by $\vartheta(\boldsymbol{\sigma}) = \alpha\mathbb{I} + \alpha^2\boldsymbol{\sigma} + \alpha^3\boldsymbol{\sigma}^2$ and $\mathbf{f}(\phi) = \beta\mathbf{r}\phi$, respectively, where \mathbf{r} is the radial vector $\mathbf{r} = (x, y, 0)^t$ and α, β are the adimensional parameters given in Example 2, assuming the values $\alpha = 5.0\text{e-}3$ and $\beta = 75$.

Figure 4 shows the approximate solutions, indicating that the cylindrical particle deforms on the faces and outer radius and having a more important displacement on the faces. Finally, as in Example 2, we observe that the lithium concentration induces the swelling of the cylindrical particle, however as on the faces Γ^B we now have zero-traction and zero concentration flux conditions coexisting, the lithium concentration is no longer maximal on the outer radius.

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